# Internal Debt and Welfare 

October 25, 2021

## Appendix

## A Derivation of the MNE's maximization problem

The MNE issues new equity $E_{t}$ in period $t$ with a price $q_{t}$ on the world capital market. The value of this equity is, thus, $q_{t} E_{t}$. Investors purchasing this equity earn next period dividends $D_{t}$ and capital gains $\dot{q}_{t} E_{t}$. They can, however, also invest in other assets in the world market and earn the interest rate $r$. They are indifferent between investing in the MNE and earning $r$ if

$$
\begin{equation*}
\frac{D_{t}+\dot{q}_{t} E_{t}}{q_{t} E_{t}}=r . \tag{A.1}
\end{equation*}
$$

Differentiate the value of equity $V_{t}=q_{t} E_{t}$ with respect to time:

$$
\begin{equation*}
\dot{V}_{t}=\dot{q}_{t} E_{t}+q_{t} \dot{E}_{t} . \tag{A.2}
\end{equation*}
$$

Our objective is to solve (A.2) for the value of equity, $V_{t}$. The net profit $\bar{\pi}_{t}^{M}$ can either be used to pay dividends $D_{t}$ or be held as retained earnings $R E_{t}$, such that

$$
\begin{equation*}
\bar{\pi}_{t}^{M}=D_{t}+R E_{t} . \tag{A.3}
\end{equation*}
$$

Furthermore, new investment can be financed either through retained earnings $R E_{t}$ or new equity issues $q_{t} \dot{E}_{t}$. Thus, we have

$$
\begin{equation*}
\left(I_{t}+C\left(I_{t}\right)\right) K_{t}=R E_{t}+q_{t} \dot{E}_{t} \tag{A.4}
\end{equation*}
$$

Use Equations (A.3),(A.4), (3) and (5) to solve for $q_{t} \dot{E}_{t}$ :

$$
\begin{equation*}
q_{t} \dot{E}_{t}=\left(I_{t}+C\left(I_{t}\right)\right) K_{t}-R E_{t}=-\pi_{t}^{M}+D_{t} \tag{A.5}
\end{equation*}
$$

Inserting (A.5) in (A.2), we get

$$
\begin{equation*}
\dot{V}_{t}=\dot{q}_{t} E_{t}-\pi_{t}^{M}+D_{t} \tag{A.6}
\end{equation*}
$$

Next, we solve (A.1) for $\dot{q}_{t} E_{t}$ and insert the resulting expression in (A.6) to get

$$
\begin{align*}
\dot{V}_{t} & =r q_{t} E_{t}-\pi_{t}^{M} \\
& =r V_{t}-\pi_{t}^{M} . \tag{A.7}
\end{align*}
$$

Using the integrating factor $e^{-r t}$, integrating (A.7) from 0 to $s$, and rearranging, we get

$$
\begin{equation*}
V_{0}=V_{s} e^{-r s}+\int_{0}^{s} \pi_{t}^{M} e^{-r t} d t \tag{A.8}
\end{equation*}
$$

Finally, evaluating at $s \rightarrow \infty$ and using the terminal condition $\lim _{s \rightarrow \infty} V_{s} e^{-r s}=0$, we get Equation (6).

## B Solution of the MNE's optimization problem

Following the assumption of a binding TCR constraint, the optimal internal debt is given by $B_{t}=b K_{t}$. Hence, the MNE maximizes Equation (6) over $I_{t}$ and $L_{t}^{m}$ subject to the equation of motion (4) and the initial condition $K(0)=K_{0}$. Let us use dynamic programming to find the optimum. Define the value function of the maximization problem as $W\left(K_{t}\right)$. The Bellman equation is

$$
\begin{equation*}
r W\left(K_{t}\right)=\max _{I_{t}, L_{t}^{m}}\left\{\pi_{t}^{M}+W_{K}\left(K_{t}\right) I_{t} K_{t}\right\}, \tag{B.1}
\end{equation*}
$$

where $W_{K}\left(K_{t}\right)$ is the derivative of the value function with respect to capital and $\pi_{t}^{M}$ is given by

$$
\begin{equation*}
\pi_{t}^{M}=F\left(K_{t}, L_{t}^{m}\right)-w_{t} L_{t}^{m}-\left(I_{t}+C\left(I_{t}\right)\right) K_{t}-C^{B}(r b) K_{t}-\tau\left[F\left(K_{t}, L_{t}^{m}\right)-w_{t} L_{t}^{m}-r b K_{t}\right] . \tag{B.2}
\end{equation*}
$$

The first-order conditions are

$$
\begin{align*}
\frac{\partial}{\partial L_{t}^{m}} & =(1-\tau)\left(F_{L}\left(K_{t}, L_{t}\right)-w_{t}\right)=0  \tag{B.3}\\
\frac{\partial}{\partial I_{t}} & =-\left(1+C^{\prime}\left(I_{t}\right)\right) K_{t}+W_{K}\left(K_{t}\right) K_{t}=0 \tag{B.4}
\end{align*}
$$

Equation (B.4) gives $W_{K}\left(K_{t}\right)=1+C^{\prime}\left(I_{t}\right)$. Differentiation of (B.4) with respect to time gives the expression $W_{K K}\left(K_{t}\right) \dot{K}_{t}=C^{\prime \prime} \dot{I}_{t}$. Moreover, using the Envelope theorem, we can differentiate the maximized Bellman equation with respect to capital to get

$$
\begin{align*}
r W_{K}\left(K_{t}\right) & =\pi_{K}^{M}+W_{K}\left(K_{t}\right) I_{t}+W_{K K}\left(K_{t}\right) I_{t} K_{t}  \tag{B.5}\\
& =F_{K}-\left(I_{t}+C\left(I_{t}\right)\right)-\tau\left(F_{K}-r b\right)-C^{B}(r b)+W_{K}\left(K_{t}\right) I_{t}+W_{K K}\left(K_{t}\right) I_{t} K_{t} .
\end{align*}
$$

Solving (B.5) for $W_{K K}\left(K_{t}\right)$ and inserting the resulting expression in $W_{K K}\left(K_{t}\right) \dot{K}_{t}=$ $C^{\prime \prime} \dot{I}_{t}$, we get

$$
\begin{equation*}
C^{\prime \prime} \dot{I}_{t}=\frac{\dot{K}_{t}}{I_{t} K_{t}}\left[W_{K}\left(K_{t}\right)\left(r-I_{t}\right)-(1-\tau) F_{K}+\left(I_{t}+C\left(I_{t}\right)\right)-\tau r b+C^{B}(r b)\right] \tag{B.6}
\end{equation*}
$$

Using Equations (4) and (B.4) to substitute for $\dot{K}_{t}$ and $W_{K}\left(K_{t}\right)$ in (B.6) and simplifying, we derive Equation (7). Equation (8) follows directly from (B.3).

## C Proof of Lemma 1

To perform the comparative dynamic analysis, I follow Wildasin (2003). Suppose that at time 0 , the government permanently increases the tax rate by $d \tau>0$.

First, derive the impact on the steady state capital stock $\widetilde{K}$, given by $\partial \widetilde{K} / \partial \tau$ (Equation (14)). Differentiate totally Equation (10a) with respect to $\widetilde{K}$ and $\tau$, taking into account that $\widetilde{L}^{m}=L^{m}(\widetilde{K})$ according to Equation (11). The resulting expression is

$$
\begin{align*}
{\left[F_{K K}+F_{K L} \frac{\partial L^{m}}{\partial \widetilde{K}}\right] \frac{\partial \widetilde{K}}{\partial \tau} } & =\frac{-r b(1-\tau)-\left[r(1-b \tau)+C^{B}(r b)\right](-1)}{(1-\tau)^{2}}, \\
\Leftrightarrow \frac{\partial \widetilde{K}}{\partial \tau} & =\frac{\left[r(1-b)+C^{B}(r b)\right]\left(F_{L L}+G_{L L}\right)}{(1-\tau)^{2} F_{K K} G_{L L}}=\frac{\left(F_{K}-r b\right)\left(F_{L L}+G_{L L}\right)}{(1-\tau) F_{K K} G_{L L}} . \tag{C.1}
\end{align*}
$$

Equation (C.1) coincides with (14) in Lemma 1.
To derive $\partial K_{t} / \partial \tau$, differentiate Equations (7) and (4) with respect to $\tau, K_{t}, \dot{K}_{t}, I_{t}$ and $\dot{I}_{t}$ :

$$
\begin{align*}
C^{\prime \prime} \frac{\partial \dot{I}_{t}}{\partial \tau} & =-(1-\tau)\left(F_{K K}+F_{K L} \frac{\partial L_{t}^{m}}{\partial K_{t}}\right) \frac{\partial K_{t}}{\partial \tau}+\left[C^{\prime \prime}\left(r-I_{t}\right)-C^{\prime \prime \prime} \dot{I}_{t}\right] \frac{\partial I_{t}}{\partial \tau}+\left(F_{K}-r b\right)  \tag{C.2}\\
\partial \dot{K}_{t} & =I_{t} \partial K_{t}+K_{t} \partial I_{t} . \tag{C.3}
\end{align*}
$$

Suppose that the economy is near steady state with $K_{t} \approx \widetilde{K}, I_{t} \approx \widetilde{I}=0, \dot{I}_{t} \approx 0$. Then,

Equation (C.3) becomes

$$
\begin{equation*}
\partial I_{t}=\frac{\partial \dot{K}_{t}}{\widetilde{K}} \tag{C.4}
\end{equation*}
$$

Moreover, we can differentiate Equation (C.4) with respect to time, which gives

$$
\begin{equation*}
\partial \dot{I}_{t}=\frac{\partial \ddot{K}_{t}}{\widetilde{K}} \tag{C.5}
\end{equation*}
$$

One can now use Equations (C.4), (C.5) and (11) to simplify (C.2):

$$
\begin{equation*}
\frac{\partial \ddot{K}_{t}}{\partial \tau}-r \frac{\partial \dot{K}_{t}}{\partial \tau}+\frac{(1-\tau) F_{K K} G_{L L} \widetilde{K}}{C^{\prime \prime}\left(F_{L L}+G_{L L}\right)} \frac{\partial K_{t}}{\partial \tau}=\frac{\widetilde{K}\left(F_{K}-r b\right)}{C^{\prime \prime}} \tag{C.6}
\end{equation*}
$$

Equation (C.6) is a second-order heterogeneous differential equation in $\partial K_{t} / \partial \tau$.
The particular solution to (C.6) is found by setting $\partial \ddot{K}_{t}=\partial \dot{K}_{t}=0$. Thus, the particular solution is

$$
\begin{equation*}
\frac{\partial K_{t}}{\partial \tau}=\frac{\left(F_{K}-r b\right)\left(F_{L L}+G_{L L}\right)}{(1-\tau) F_{K K} G_{L L}} \tag{C.7}
\end{equation*}
$$

To find the solution to the homogeneous part (i.e., the left-hand side) of (C.6), we suppose that the solution is of the form $\partial K_{t} / \partial \tau=A e^{\mu t}$, where $A$ is an undetermined constant. Under the exponential functional form, we have $\partial \dot{K}_{t} / \partial \tau=\mu \partial K_{t} / \partial \tau$ and $\partial \ddot{K}_{t} / \partial \tau=\mu^{2} \partial K_{t} / \partial \tau$. Hence, the homogeneous part of (C.6) can be rewritten as

$$
\begin{equation*}
\mu^{2}-r \mu+\frac{(1-\tau) F_{K K} G_{L L} \widetilde{K}}{C^{\prime \prime}\left(F_{L L}+G_{L L}\right)}=0 \tag{C.8}
\end{equation*}
$$

Equation (C.8) has two solutions for $\mu$, given by

$$
\begin{equation*}
\mu_{1}=\frac{r-\sqrt{r^{2}-\frac{4(1-\tau) F_{K K} G_{L L} \widetilde{K}}{C^{\prime \prime}\left(F_{L L}+G_{L L}\right)}}}{2}<0, \quad \mu_{2}=\frac{r+\sqrt{r^{2}-\frac{4(1-\tau) F_{K K} G_{L L} \widetilde{K}}{C^{\prime \prime}\left(F_{L L}+G_{L L}\right)}}}{2}>0 \tag{C.9}
\end{equation*}
$$

Therefore, Equation (C.8) has one positive and one negative root. The solution to the homogeneous part is, thus,

$$
\begin{equation*}
\frac{\partial K_{t}}{\partial \tau}=A_{1} e^{\mu_{1} t}+A_{2} e^{\mu_{2} t} \tag{C.10}
\end{equation*}
$$

where $A_{1}$ and $A_{2}$ are undetermined coefficients. The general solution is the sum of the
homogeneous and particular solutions:

$$
\begin{equation*}
\frac{\partial K_{t}}{\partial \tau}=\frac{\left(F_{K}-r b\right)\left(F_{L L}+G_{L L}\right)}{(1-\tau) F_{K K} G_{L L}}+A_{1} e^{\mu_{1} t}+A_{2} e^{\mu_{2} t} \tag{C.11}
\end{equation*}
$$

Invoking the initial condition $\partial K_{0} / \partial \tau=0$ and the terminal condition $\lim _{t \rightarrow \infty} \partial K_{t} / \partial \tau=$ $\partial \widetilde{K} / \partial \tau$, one gets $A_{1}=-\partial \widetilde{K} / \partial \tau$ and $A_{2}=0$. This completes the proof of Lemma 1.

## D Derivation of the optimal tax rate (Equation (18))

The government's objective function is

$$
\begin{align*}
& \int_{0}^{\infty} \Omega_{t} e^{-r t} d t=\int_{0}^{\infty}\left(X_{t}^{W}+\beta X_{t}^{E}\right) e^{-r t} d t  \tag{D.1}\\
& =\int_{0}^{\infty}\left\{\tau\left[F\left(K_{t}, L_{t}^{m}\right)-r b K_{t}\right]+(1-\tau) w_{t} L_{t}^{m}+G\left(L_{t}^{d}\right)-(1-\tau)(1-\beta)\left[G\left(L_{t}^{d}\right)-w_{t} L_{t}^{d}\right]\right\} e^{-r t} d t .
\end{align*}
$$

It maximizes (D.1) subject to $L_{t}^{m}=L_{t}^{m}\left(K_{t}\right), L_{t}^{d}=L_{t}^{d}\left(K_{t}\right), w_{t}=w_{t}\left(K_{t}\right)$ and Equation (12). The first-order condition is

$$
\begin{align*}
\frac{\partial}{\partial \tau}= & \int_{0}^{\infty}\left\{F\left(K_{t}, L_{t}^{m}\right)-r b K_{t}-w_{t} L_{t}^{m}+(1-\beta)\left[G\left(L_{t}^{d}\right)-w_{t} L_{t}^{d}\right]\right. \\
& +\left[\tau\left(F_{K}-r b\right)+\left(\tau F_{L}+(1-\tau) w_{t}\right) \frac{\partial L_{t}^{m}}{\partial K_{t}}+(1-\tau)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right] \frac{\partial w_{t}}{\partial K_{t}}\right. \\
& \left.\left.+\left[G_{L}-(1-\tau)(1-\beta)\left(G_{L}-w_{t}\right)\right] \frac{\partial L_{t}^{d}}{\partial K_{t}}\right] \frac{\partial K_{t}}{\partial \tau}\right\} e^{-r t} d t=0 \tag{D.2}
\end{align*}
$$

Using the labor demand equations $F_{L}=w$ and $G_{L}=w$, we can simplify (D.2):

$$
\begin{align*}
\frac{\partial}{\partial \tau}= & \int_{0}^{\infty}\left\{F\left(K_{t}, L_{t}^{m}\right)-r b K_{t}-w_{t} L_{t}^{m}+(1-\beta)\left[G\left(L_{t}^{d}\right)-w_{t} L_{t}^{d}\right]\right. \\
& \left.+\left[\tau\left(F_{K}-r b\right)+(1-\tau)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right] \frac{\partial w_{t}}{\partial K_{t}}\right] \frac{\partial K_{t}}{\partial \tau}\right\} e^{-r t} d t=0 \tag{D.3}
\end{align*}
$$

Following Wildasin (2003), I assume that the economy is near its steady state, such that $K_{t} \approx \widetilde{K}, L_{t}^{m} \approx \widetilde{L}^{m}, L_{t}^{d} \approx \widetilde{L}^{d}, w_{t} \approx \widetilde{w}$ and $\partial K_{t} / \partial \tau=\partial \widetilde{K} / \partial \tau\left(1-e^{\mu_{1} t}\right)$. Thus, (D.3)
becomes

$$
\begin{align*}
& \int_{0}^{\infty}\left\{F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left[G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right]\right.  \tag{D.4}\\
& \left.+\left[\tau\left(F_{K}-r b\right)+(1-\tau)\left[\widetilde{L}^{m}+(1-\beta) \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \widetilde{K}}\right] \frac{\partial \widetilde{K}}{\partial \tau}\left(1-e^{\mu_{1} t}\right)\right\} e^{-r t} d t=0
\end{align*}
$$

where $\partial \widetilde{w} / \partial \widetilde{K}$ is the value of $\partial w_{t} / \partial K_{t}$, when evaluated at the steady state. We use (11) and (C.1) to define $\partial \widetilde{w} / \partial \tau$ as

$$
\begin{equation*}
\frac{\partial \widetilde{w}}{\partial \tau} \equiv \frac{\partial \widetilde{w}}{\partial \widetilde{K}} \frac{\partial \widetilde{K}}{\partial \tau}=\frac{\left(F_{K}-r b\right) F_{L K}}{(1-\tau) F_{K K}}<0 \tag{D.5}
\end{equation*}
$$

Integrate the left-hand side of (D.4) to get

$$
\begin{align*}
0= & F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left[G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right] \\
& -\frac{\mu_{1}}{r-\mu_{1}}\left[\tau\left(F_{K}-r b\right) \frac{\partial \widetilde{K}}{\partial \tau}+(1-\tau)\left[\widetilde{L}^{m}+(1-\beta) \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \tau}\right] . \tag{D.6}
\end{align*}
$$

We can now use the constant returns property of the production function $F(\cdot)$, which allows $F(\cdot)$ to be represented as $F\left(K, L^{m}\right)=F_{K} K+F_{L} L^{m}=F_{K} K+w L^{m}$. Thus, (D.6) becomes

$$
\begin{align*}
0= & \left(F_{K}-r b\right) \widetilde{K}+(1-\beta)\left[G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right] \\
& -\frac{\mu_{1}}{r-\mu_{1}}\left[\tau\left(F_{K}-r b\right) \frac{\partial \widetilde{K}}{\partial \tau}+(1-\tau)\left[\widetilde{L}^{m}+(1-\beta) \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \tau}\right] . \tag{D.7}
\end{align*}
$$

Moreover, the partial derivative $F_{K}$ is homogeneous of degree zero, which means that $0 \cdot F_{K}=F_{K K} K+F_{K L} L^{m}$. Therefore, we get

$$
\begin{equation*}
(1-\tau) \widetilde{L}^{m} \frac{\partial \widetilde{w}}{\partial \tau}=\frac{(1-\tau) \widetilde{L}^{m}\left(F_{K}-r b\right) F_{L K}}{(1-\tau) F_{K K}}=-\left(F_{K}-r b\right) \widetilde{K} \tag{D.8}
\end{equation*}
$$

Inserting (D.8) in (D.7), denoting the optimal tax as $\tau^{*}$, and rearranging gives Equation (18).

## E Proof of Proposition 1

We use Equations (10a) and (D.6), which determine the steady state capital stock and optimal tax rate, respectively, to derive the effects of a change in $b$ on $\tau^{*}$ and $\widetilde{K}$.

Using (C.1), (D.8) and the labor market clearing condition (9) to simplify (D.6), we can express (10a) and (D.6) as

$$
\begin{align*}
0= & F_{K}\left(\widetilde{K}, \widetilde{L}^{m}\right)\left(1-\tau^{*}\right)-r\left(1-b \tau^{*}\right)-C^{B}(r b),  \tag{E.1}\\
0= & F\left(\widetilde{K}, \widetilde{L}^{m}\right)-b r \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left[G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right] \\
& -\frac{\mu_{1}}{r-\mu_{1}}\left(F_{K}\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b\right)\left[\tau^{*} \frac{\partial \widetilde{K}}{\partial \tau}-\frac{\widetilde{K}\left(1-\beta \widetilde{L}^{d}\right)}{\widetilde{L}^{m}}\right] . \tag{E.2}
\end{align*}
$$

The next step is to totally differentiate (E.1) and (E.2) with respect to $\widetilde{K}, \tau^{*}$, and $b$. Note, first, that $\mu_{1}$ depends on $\tau$ and $\widetilde{K}$ in the following way:

$$
\begin{align*}
& \frac{d \mu_{1}}{d \tau}=\frac{-F_{K K} G_{L L} \widetilde{K}}{C^{\prime \prime}\left(F_{L L}+G_{L L}\right) \sqrt{r^{2}-\frac{4(1-\tau) F_{K K} G_{L L} \tilde{K}}{c\left(F_{L L}+G_{L L}\right)}}}=-\frac{\mu_{1}\left(r-\mu_{1}\right)}{\left(r-2 \mu_{1}\right)(1-\tau)}  \tag{E.3}\\
& \frac{d \mu_{1}}{d \widetilde{K}}=\frac{(1-\tau) F_{K K} G_{L L}(1+\xi)}{C^{\prime \prime}\left(F_{L L}+G_{L L}\right) \sqrt{r^{2}-\frac{4(1-\tau) F_{K K} G_{L L} \widetilde{K}}{c\left(F_{L L}+G_{L L}\right)}}}=\frac{\mu_{1}\left(r-\mu_{1}\right)(1+\xi)}{\left(r-2 \mu_{1}\right) \widetilde{K}} \tag{E.4}
\end{align*}
$$

where
$\xi \equiv \widetilde{K} \frac{\left(F_{K K K}+F_{K K L} \frac{\partial \widetilde{L}^{m}}{\partial \widetilde{K}}\right) G_{L L}\left(F_{L L}+G_{L L}\right)-F_{K K}\left[\frac{\partial \widetilde{L}^{m}}{\partial \widetilde{K}}\left(G_{L L L} F_{L L}+G_{L L} F_{L L L}\right)+G_{L L} F_{L L K}\right]}{F_{K K} G_{L L}\left(F_{L L}+G_{L L}\right)}$.

Using Equations (E.3) (E.4), as well as (11) and (14), the total differential of (E.1) and (E.2) is

$$
\underbrace{\left(\begin{array}{ll}
a_{11} & a_{12}  \tag{E.6}\\
a_{21} & a_{22}
\end{array}\right)}_{=J}\binom{d \widetilde{K}}{d \tau^{*}}=\binom{-b_{1}}{-b_{2}} d b,
$$

where

$$
\begin{align*}
a_{11} \equiv & \left(1-\tau^{*}\right) \frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}},  \tag{E.7a}\\
a_{12} \equiv & -\left(F_{K}-r b\right),  \tag{E.7b}\\
a_{21} \equiv & \frac{F_{K}-r b}{r-\mu_{1}}\left[\frac{r\left(1-\tau^{*}\right)-\mu_{1}\left(1+\tau^{*}\right)}{1-\tau^{*}}-\frac{\mu_{1}(1-\beta) F_{L L}}{\widetilde{L}^{m}\left(F_{L L}+G_{L L}\right)}-\frac{\mu_{1} \tau^{*}}{\left(r-2 \mu_{1}\right) \widetilde{K}} \frac{\partial \widetilde{K}}{\partial \tau}\left(r+2 \mu_{1} \xi\right)\right] \\
& +\frac{\widetilde{K}\left(1-\beta \widetilde{L}^{d}\right)}{\left(r-\mu_{1}\right) \widetilde{L}^{m}}\left[r \frac{G_{L L} F_{K K}}{F_{L L}+G_{L L}}+\frac{\mu_{1}\left(F_{K}-r b\right)}{\left(r-2 \mu_{1}\right) \widetilde{K}}\left(2\left(r-\mu_{1}\right)+r \xi\right)\right] \tag{E.7c}
\end{align*}
$$

$$
\begin{align*}
a_{22} & \equiv-\frac{\mu_{1}\left(F_{K}-r b\right)\left[\frac{\partial \widetilde{K}}{\partial \tau}\left(r\left(1-\tau^{*}\right)-2 \mu_{1}\right)+r \frac{\widetilde{K}\left(1-\beta \widetilde{L}^{d}\right)}{\widetilde{L}^{m}}\right]}{\left(r-\mu_{1}\right)\left(r-2 \mu_{1}\right)\left(1-\tau^{*}\right)},  \tag{E.7d}\\
b_{1} & \equiv r\left(\tau^{*}-C^{\left.B^{\prime}(r b)\right)}\right.  \tag{E.7e}\\
b_{2} & \equiv-r\left[\widetilde{K}-\frac{\mu_{1}}{\left(r-\mu_{1}\right)}\left(2 \tau^{*} \frac{\partial \widetilde{K}}{\partial \tau}-\frac{\widetilde{K}\left(1-\beta \widetilde{L}^{d}\right)}{\widetilde{L}^{m}}\right)\right] \tag{E.7f}
\end{align*}
$$

The determinant of the matrix $J$ is given by

$$
\begin{align*}
|J|= & a_{11} a_{22}-a_{12} a_{21} \\
= & \left\{\frac{\widetilde{K}\left(1-\beta \widetilde{L}^{d}\right)}{\widetilde{L}^{m}}\left(r\left(r-3 \mu_{1}\right) \frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}}-\frac{\mu_{1}\left(F_{K}-r b\right)}{\widetilde{K}}\left(2\left(r-\mu_{1}\right)+r \xi\right)\right)\right. \\
& +\frac{\left(F_{K}-r b\right)}{1-\tau^{*}}\left[\left(r-2 \mu_{1}\right)\left(r\left(1-\tau^{*}\right)-\mu_{1}\left(2+\tau^{*}\right)-\mu_{1}\left(1-\tau^{*}\right) \frac{(1-\beta) F_{L L}}{\widetilde{L}^{m}\left(F_{L L}+G_{L L}\right)}\right)\right. \\
& \left.\left.+\mu_{1} \tau^{*}\left(r-\frac{1-\tau^{*}}{\widetilde{K}} \frac{\partial \widetilde{K}}{\partial \tau}\left(r+2 \mu_{1} \xi\right)\right)\right]\right\} \frac{F_{K}-r b}{\left(r-\mu_{1}\right)\left(r-2 \mu_{1}\right)}>0 . \tag{E.8}
\end{align*}
$$

The determinant of $J$ must be positive as required by the second-order condition of the government's maximization problem (i.e., the derivative of (D.6) with respect to $\tau$ ). Using Cramer's rule, the effects of $b$ on the steady state capital stock and tax rate are:

$$
\begin{align*}
\frac{d \widetilde{K}}{d b} & =\frac{1}{|J|}\left|\begin{array}{cc}
-b_{1} & a_{12} \\
-b_{2} & a_{22}
\end{array}\right|=\frac{b_{2} a_{12}-b_{1} a_{22}}{|J|} \\
& =\frac{r\left(F_{K}-r b\right)}{|J|\left(r-2 \mu_{1}\right)\left(r-\mu_{1}\right)\left(1-\tau^{*}\right)}\left\{\mu _ { 1 } \tau ^ { * } \frac { \partial \widetilde { K } } { \partial \tau } \left[2 \mu_{1}\left(1-2 \tau^{*}\right)-r\left(1-\tau^{*}\right)\right.\right. \\
& \left.-\frac{C^{B \prime}}{\tau^{*}}\left(r\left(1-\tau^{*}\right)-2 \mu_{1}\right)\right]+\widetilde{K}\left[\left(r-\mu_{1}\right)\left(r-2 \mu_{1}\right)\left(1-\tau^{*}\right)\right. \\
& \left.\left.+\mu_{1} \frac{\left(1-\beta \widetilde{L}^{d}\right)}{\widetilde{L}^{m}}\left(r-2 \mu_{1}\left(1-\tau^{*}\right)-C^{B \prime} r\right)\right]\right\},  \tag{E.9}\\
\frac{d \tau^{*}}{d b} & =\frac{1}{|J|}\left|\begin{array}{ll}
a_{11} & -b_{1} \\
a_{21} & -b_{2}
\end{array}\right|=\frac{b_{1} a_{21}-b_{2} a_{11}}{|J|} \\
& =\frac{r}{|J|\left(r-\mu_{1}\right)}\left\{( F _ { K } - r b ) \tau ^ { * } \left[r-\frac{\mu_{1}\left(3-\tau^{*}\right)}{1-\tau^{*}}-\mu_{1} \frac{(1-\beta) F_{L L}}{\widetilde{L}^{m}\left(F_{L L}+G_{L L}\right)}\right.\right.  \tag{E.10}\\
& \left.-\frac{\mu_{1} \tau^{*}\left(r+2 \mu_{1} \xi\right)}{\left(r-2 \mu_{1}\right) \widetilde{K}} \frac{\partial \widetilde{K}}{\partial \tau}\right]+\left(r-\mu_{1}\right)\left(1-\tau^{*}\right) \frac{F_{K K} G_{L L} \widetilde{K}}{F_{L L}+G_{L L}}+\frac{\widetilde{K}\left(1-\beta \widetilde{L^{d}}\right)}{\widetilde{L}^{m}} .
\end{align*}
$$

$$
\left.\cdot\left[\frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}}\left(\tau^{*} r+\left(1-\tau^{*}\right) \mu_{1}\right)+\frac{\tau^{*} \mu_{1}\left(F_{K}-r b\right)}{\left(r-2 \mu_{1}\right) \widetilde{K}}\left(2\left(r-\mu_{1}\right)+r \xi\right)\right]\right\}-\frac{r C^{B \prime} a_{21}}{|J|}
$$

The expression (E.9) contains only negative terms in its first row and both negative and positive terms in the second and third rows. The change in $\widetilde{K}$ has, thus, an ambiguous sign. The same is true for (E.10): while the first row of (E.10) is positive, the second and third rows are either positive or negative.

We are interested in the impact of $d b$, starting from zero internal financing, i.e., $b=$ 0 . Therefore, we evaluate (E.9) and (E.10) at $b=0$. Taking into account $C^{B \prime}(0)=0$, we get

$$
\begin{align*}
\frac{d \widetilde{K}}{d b}(b=0) & =\frac{r F_{K}}{|J|\left(r-2 \mu_{1}\right)\left(r-\mu_{1}\right)\left(1-\tau^{*}\right)}\left\{\mu_{1} \tau^{*} \frac{\partial \widetilde{K}}{\partial \tau}\left[2 \mu_{1}\left(1-2 \tau^{*}\right)-r\left(1-\tau^{*}\right)\right]\right. \\
& \left.+\widetilde{K}\left[\left(r-\mu_{1}\right)\left(r-2 \mu_{1}\right)\left(1-\tau^{*}\right)+\mu_{1} \frac{\left(1-\beta \widetilde{L}^{d}\right)}{\widetilde{L}^{m}}\left(r-2 \mu_{1}\left(1-\tau^{*}\right)\right)\right]\right\},  \tag{E.11}\\
\frac{d \tau^{*}}{d b}(b=0) & =\frac{r}{|J|\left(r-\mu_{1}\right)}\left\{F _ { K } \tau ^ { * } \left[r-\frac{\mu_{1}\left(3-\tau^{*}\right)}{1-\tau^{*}}-\mu_{1} \frac{(1-\beta) F_{L L}}{\widetilde{L}^{m}\left(F_{L L}+G_{L L}\right)}\right.\right.  \tag{E.12}\\
& \left.-\frac{\mu_{1} \tau^{*}\left(r+2 \mu_{1} \xi\right)}{\left(r-2 \mu_{1}\right) \widetilde{K}} \frac{\partial \widetilde{K}}{\partial \tau}\right]+\left(r-\mu_{1}\right)\left(1-\tau^{*}\right) \frac{F_{K K} G_{L L} \widetilde{K}}{F_{L L}+G_{L L}}+\frac{\widetilde{K}\left(1-\beta \widetilde{L^{d}}\right)}{\widetilde{L}^{m}} . \\
& \left.\cdot\left[\frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}}\left(\tau^{*} r+\left(1-\tau^{*}\right) \mu_{1}\right)+\frac{\tau^{*} \mu_{1}\left(F_{K}-r b\right)}{\left(r-2 \mu_{1}\right) \widetilde{K}}\left(2\left(r-\mu_{1}\right)+r \xi\right)\right]\right\} .
\end{align*}
$$

To prove the first part of Proposition 1, take the limit of (E.11) when $\mu_{1}$ approaches $-\infty$ :

$$
\begin{align*}
\lim _{\mu_{1} \rightarrow-\infty} \frac{d \widetilde{K}}{d b}(b=0)= & \frac{r F_{K}}{|J|\left(1-\tau^{*}\right)}\left[\frac{\partial \widetilde{K}}{\partial \tau}\left[\tau^{*}\left(1-2 \tau^{*}\right)\right]-\widetilde{K}(1-\beta) \frac{\widetilde{L}^{d}}{\widetilde{L}^{m}}\left(1-\tau^{*}\right)\right]<0 \\
& \text { if } \quad \tau^{*}<\frac{1}{2}, \beta<1 \tag{E.13}
\end{align*}
$$

The limit of (E.12) when $\mu_{1} \rightarrow-\infty$ is difficult to sign due to the presence of third derivatives in the term $\xi$. Therefore, instead of directly evaluating the change in the tax rate, we evaluate it indirectly. Note that the change in the capital stock $\widetilde{K}$ can be split in two effects: a direct effect of $b$ on $\widetilde{K}$ and an indirect effect through the change in the tax rate $\tau^{*}$ :

$$
\begin{equation*}
\frac{d \widetilde{K}}{d b}=\frac{\partial \widetilde{K}}{\partial \tau} \frac{d \tau^{*}}{d b}+\frac{\partial \widetilde{K}}{\partial b} \tag{E.14}
\end{equation*}
$$

where the direct effect $\partial \widetilde{K} / \partial b$ is derived by totally differentiating Equation (10a) with respect to $\widetilde{K}$ and $b$ :

$$
\begin{equation*}
\frac{\partial \widetilde{K}}{\partial b}=\frac{r\left(C^{B \prime}-\tau^{*}\right)\left(F_{L L}+G_{L L}\right)}{\left(1-\tau^{*}\right) F_{K K} G_{L L}}>0 . \tag{E.15}
\end{equation*}
$$

The above term is positive because we focus only on internal debt ratios $b<\hat{b}$, where, by definition, $C^{B^{\prime}}(r \hat{b})=\tau$. Owing to the convexity of $C^{B}(\cdot)$, we have $C^{B^{\prime}}(r b)-\tau<0$ for all $b<\hat{b}$. Hence, it is also positive when evaluated at $b=0$. Thus, we can solve for $d \tau^{*} / d b$ from Equation (E.14):

$$
\begin{equation*}
\frac{d \tau^{*}}{d b}=\frac{\frac{d \tilde{K}}{d b}-\frac{\partial \tilde{K}}{\partial b}}{\frac{\partial \tilde{K}}{\partial \tau}}>0, \quad \text { if } \quad \mu_{1} \rightarrow-\infty, b=0, \beta<1 \quad \text { and } \tau^{*}<\frac{1}{2} \tag{E.16}
\end{equation*}
$$

Thus, in a static model, $\tau^{*}<1 / 2, \beta<1$ is sufficient for the introduction of internal debt to have a positive effect on the optimal tax rate.

To prove the second part of Proposition 1, evaluate (E.11) and (E.12) at $\beta=1$. Note first that, in this case, the optimal tax rate is determined by

$$
\begin{equation*}
\frac{\tau^{*}}{\widetilde{K}} \frac{\partial \widetilde{K}}{\partial \tau}=\frac{r}{\mu_{1}} \tag{E.17}
\end{equation*}
$$

where (E.17) is Equation (18), evaluated at $\beta=1$. Evaluating Equations (E.11) and (E.12) at $\beta=1$ and using (E.17), one gets

$$
\begin{align*}
\frac{d \widetilde{K}}{d b}(b=0, \beta=1)= & -\frac{r^{2} F_{K} \widetilde{K} \mu_{1} \tau^{*}}{|J|\left(r-2 \mu_{1}\right)\left(r-\mu_{1}\right)\left(1-\tau^{*}\right)}>0  \tag{E.18}\\
\frac{d \tau^{*}}{d b}(b=0, \beta=1)= & \frac{r}{|J|\left(r-\mu_{1}\right)}\left\{F_{K} \tau^{*}\left[r-\frac{\mu_{1}\left(3-\tau^{*}\right)}{1-\tau^{*}}-\frac{r\left(r+2 \mu_{1} \xi\right)}{\left(r-2 \mu_{1}\right)}\right]\right.  \tag{E.19}\\
& +\left(r-\mu_{1}\right)\left(1-\tau^{*}\right) \frac{F_{K K} G_{L L} \widetilde{K}}{F_{L L}+G_{L L}}+\widetilde{K}\left[\frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}}\left(\tau^{*} r+\left(1-\tau^{*}\right) \mu_{1}\right)\right. \\
& \left.\left.+\frac{\tau^{*} \mu_{1} F_{K}}{\left(r-2 \mu_{1}\right) \widetilde{K}}\left(2\left(r-\mu_{1}\right)+r \xi\right)\right]\right\}
\end{align*}
$$

Equation (E.18) is positive. To sign (E.19), rewrite (E.17) in the case $b=0$ using (C.1):

$$
\begin{equation*}
\frac{F_{K K} G_{L L} \widetilde{K} r}{F_{L L}+G_{L L}}=\frac{\tau^{*} F_{K} \mu_{1}}{\left(1-\tau^{*}\right)} \tag{E.20}
\end{equation*}
$$

Inserting (E.20) in (E.19) and simplifying, one gets

$$
\begin{equation*}
\frac{d \tau^{*}}{d b}(b=0, \beta=1)=\frac{r F_{K} \mu_{1} \tau^{*}\left[2 \mu_{1}-r\left(2-\tau^{*}\right)-\left(1-\tau^{*}\right) r \xi\right]}{|J|\left(r-\mu_{1}\right)\left(r-2 \mu_{1}\right)\left(1-\tau^{*}\right)} . \tag{E.21}
\end{equation*}
$$

We now evaluate $|J|$ in the case $\beta=1, b=0$ :

$$
\begin{equation*}
|J|(b=0, \beta=1)=\frac{F_{K}^{2} \mu_{1}}{\left(r-\mu_{1}\right)\left(r-2 \mu_{1}\right)\left(1-\tau^{*}\right)}\left[\left(2-\tau^{*}\right)\left(\mu_{1}-r\right)-\left(1-\tau^{*}\right) r \xi\right]>0 \tag{E.22}
\end{equation*}
$$

The determinant is positive, and, thus, the second-order condition is satisfied, if $\xi>$ $\left(2-\tau^{*}\right)\left(\mu_{1}-r\right) /\left(r\left(1-\tau^{*}\right)\right)$. We use this condition to derive a lower bound for (E.21), which is positive:

$$
\begin{equation*}
\frac{d \tau^{*}}{d b}(b=0, \beta=1)>\frac{r F_{K} \mu_{1}^{2} \tau^{*}}{|J|\left(r-\mu_{1}\right)\left(r-2 \mu_{1}\right)\left(1-\tau^{*}\right)}>0 . \tag{E.23}
\end{equation*}
$$

Hence, the change in the optimal tax rate has a positive lower bound and must be positive. Together, Equations (E.18) and (E.23) prove part (b) of Proposition 1 for $\beta=1$. Since both (E.9) and (E.10) are continuous in $\beta$ there exist values of $\beta$ close but not equal to one for which $d \widetilde{K} / d b>0$ and $d \tau^{*} / d b>0$. Denote the lowest value of $\beta$ for which these results hold as $\hat{\beta}$. Then, for $\beta \in[\hat{\beta}, 1]$, the steady state capital stock and optimal tax rate are increasing in the TCR.

Lastly, for all values of $\beta$ not yet considered, i.e., $\beta \in[0, \hat{\beta}[$, the effects of an increase in $b$ are given by (E.9) and (E.10) and are ambiguous.

## F Welfare Effects of Internal Debt

To derive the welfare effects of internal debt use, we begin by expressing the steady state welfare as

$$
\begin{equation*}
\widetilde{\Omega}=\tau^{*}\left[F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}\right]+\left(1-\tau^{*}\right) \widetilde{w} \widetilde{L}^{m}+G\left(\widetilde{L}^{d}\right)-\left(1-\tau^{*}\right)(1-\beta)\left[G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right] . \tag{F.1}
\end{equation*}
$$

First, I prove the following Lemma:

Lemma 2. Suppose that, starting from $b=0$, the government allows internal debt by a TCR relaxation $d b>0$ in period 0 . If $\mu_{1} \rightarrow-\infty$, the economy is static and $\Omega_{t}=\Omega$
for all $t>0$. If $\beta<(=) 1$, then welfare increases (remains unchanged):

$$
\frac{d \Omega}{d b} \begin{cases}>0, & \text { if } \beta<1  \tag{F.2}\\ =0, & \text { if } \beta=1\end{cases}
$$

Proof: We start by deriving the change in $\widetilde{\Omega}$ by differentiating welfare with respect to $b$, taking into account the effects of $b$ on $\tau^{*}$ and $\widetilde{K}$. The resulting expression is ${ }^{1}$

$$
\begin{align*}
\frac{d \widetilde{\Omega}}{d b}= & -r \tau^{*} \widetilde{K}+\left[F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right] \frac{d \tau^{*}}{d b} \\
& +\left[\tau^{*}\left(F_{K}-r b\right)+\left(1-\tau^{*}\right) \frac{\partial \widetilde{w}}{\partial \widetilde{K}}\left(\widetilde{L}^{m}+(1-\beta) \widetilde{L}^{d}\right)\right] \frac{d \widetilde{K}}{d b} \tag{F.3}
\end{align*}
$$

Using the government's first-order condition (D.6), we can substitute for the term in brackets in the second row of (F.3). Moreover, we can express $F(\cdot)$ as $F=F_{K} K+F_{L} L^{m}$. Equation (F.3) becomes

$$
\begin{equation*}
\frac{d \widetilde{\Omega}}{d b}=-r \tau^{*} \widetilde{K}+\left[\left(F_{K}-r b\right) \widetilde{K}+(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right]\left[\frac{d \tau^{*}}{d b}+\frac{r-\mu_{1}}{\mu_{1}} \frac{\frac{d \widetilde{K}}{d b}}{\frac{\partial \widetilde{K}}{\partial \tau}}\right] . \tag{F.4}
\end{equation*}
$$

We can split the effect of $b$ on $\widetilde{K}$ using (E.14) and (E.15). Thus, the welfare change becomes

$$
\begin{align*}
\frac{d \widetilde{\Omega}}{d b} & =-r \tau^{*} \widetilde{K}+\left[\left(F_{K}-r b\right) \widetilde{K}+(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right]\left[\frac{d \tau^{*}}{d b}+\frac{r-\mu_{1}}{\mu_{1}}\left(\frac{d \tau^{*}}{d b}+\frac{\frac{\partial \widetilde{K}}{\partial b}}{\frac{\partial \widetilde{\widetilde{ }}}{\partial \tau}}\right)\right] \\
& =-r \tau^{*} \widetilde{K}+\left[\left(F_{K}-r b\right) \widetilde{K}+(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right] \frac{r}{\mu_{1}}\left[\frac{d \tau^{*}}{d b}+\frac{\left(r-\mu_{1}\right)\left(C^{B^{\prime}}-\tau^{*}\right)}{\left(F_{K}-r b\right)}\right] . \tag{F.5}
\end{align*}
$$

Further simplification of (F.5) gives:

$$
\begin{align*}
\frac{d \widetilde{\Omega}}{d b}= & -\frac{r}{\mu_{1}}\left\{\widetilde{K}\left[r\left(\tau^{*}-C^{B \prime}\right)+\mu_{1} C^{B \prime}\right]+\frac{\left(\tau^{*}-C^{B \prime}\right)\left(r-\mu_{1}\right)}{F_{K}-r b}(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right. \\
& \left.-\left[\left(F_{K}-r b\right) \widetilde{K}+(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right] \frac{d \tau^{*}}{d b}\right\} \tag{F.6}
\end{align*}
$$

The first row of (F.6) is positive for sufficiently small $b$, while the second row is negative for $d \tau^{*} / d b>0$. Hence, the net change in $\widetilde{\Omega}$ is indeterminate.

In the case $\mu_{1} \rightarrow-\infty$, the welfare effect coincides with the results from Hong and

[^0]Smart (2010). To prove this statement, evaluate (F.6) at $\mu_{1} \rightarrow-\infty$ to get

$$
\begin{equation*}
\lim _{\mu_{1} \rightarrow-\infty} \frac{d \widetilde{\Omega}}{d b}=r\left[\frac{\left(\tau^{*}-C^{B^{\prime}}\right)(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)}{F_{K}-r b}-C^{B^{\prime}} \widetilde{K}\right]>0, \quad \text { if } b=0, \beta<1 \tag{F.7}
\end{equation*}
$$

Evaluated at $b=0, \beta<1$, the whole expression is positive because of $C^{B^{\prime}}(0)=0$.
Moreover, in the case $\mu_{1} \rightarrow-\infty$, the economy is static and $d \Omega_{t}=d \widetilde{\Omega} \equiv d \Omega$ for all $t>0$, while period 0 with the initial condition $d K_{0}=0$ cannot be observed. Thus, (F.7) holds for all periods $t>0$.

Now, I proceed with the proof of Proposition 2. Evaluate (F.6) at $\beta=1$ :

$$
\begin{equation*}
\frac{d \widetilde{\Omega}}{d b}(\beta=1)=-\frac{r \widetilde{K}}{\mu_{1}}\left[r\left(\tau^{*}-C^{B^{\prime}}\right)+\mu_{1} C^{B^{\prime}}-\left(F_{K}-r b\right) \frac{d \tau^{*}}{d b}(\beta=1)\right] . \tag{F.8}
\end{equation*}
$$

Use Equations (C.1) and (E.15) to derive the expression

$$
\begin{equation*}
\frac{\partial \widetilde{K}}{\partial b}=\frac{r\left(C^{B \prime}-\tau^{*}\right)}{\left(F_{K}-r b\right)} \frac{\partial \widetilde{K}}{\partial \tau} \tag{F.9}
\end{equation*}
$$

Equations (F.9) and (E.14) together give

$$
\begin{equation*}
\frac{d \widetilde{K}}{d b}=\frac{\partial \widetilde{K}}{\partial \tau} \frac{d \tau^{*}}{d b}+\frac{\partial \widetilde{K}}{\partial b}=\frac{\partial \widetilde{K}}{\partial \tau}\left[\frac{d \tau^{*}}{d b}+\frac{r\left(C^{B \prime}-\tau^{*}\right)}{F_{K}-r b}\right] \tag{F.10}
\end{equation*}
$$

To simplify (F.8), evaluate (F.10) at $\beta=1$ and insert it in (F.8):

$$
\begin{equation*}
\frac{d \widetilde{\Omega}}{d b}(\beta=1)=r \widetilde{K}\left[\frac{\left(F_{K}-r b\right) \frac{d \widetilde{K}}{d b}(\beta=1)}{\mu_{1} \frac{\partial \widetilde{K}}{\partial \tau}}-C^{B \prime}\right]>0, \quad \text { if } b=0 . \tag{F.11}
\end{equation*}
$$

Evaluated at $b=0$, the first term in brackets in (F.11) is unambiguously positive, while the second term is zero. Thus, (F.11) is positive at $b=0$, which proves Equation (22) from Proposition 2. Since welfare is continuous in $\beta$, this result holds also for values of $\beta$ sufficiently close but not equal to one. Define the lowest value of $\beta$ that satisfies (F.11) as $\underline{\beta}^{1}$. Then, (F.11) is satisfied for $\beta \in\left[\underline{\beta}^{1}, 1\right]$. To derive the short term welfare change, define short term welfare $\Omega_{0}$ as

$$
\begin{align*}
\Omega_{0}= & \tau^{*}\left[F\left(K_{0}, L_{0}^{m}\right)-r b K_{0}\right]+\left(1-\tau^{*}\right) w_{0} L_{0}^{m}+G\left(L_{0}^{d}\right) \\
& -\left(1-\tau^{*}\right)(1-\beta)\left[G\left(L_{0}^{d}\right)-w_{0} L_{0}^{d}\right], \tag{F.12}
\end{align*}
$$

where a subscript 0 denotes the initial period where the economy is in steady state (prior to the disturbance) such that $K_{0}=\widetilde{K}, L_{0}^{m}=\widetilde{L}^{m}, w_{0}=\widetilde{w}, L_{0}^{d}=\widetilde{L}^{d}$. The capital stock
cannot change in time period zero, $d K_{0} / d b=0$, as it is a stock variable. Consequently, the wage rate and the labor demands also remain unchanged at time period 0 . Hence, the initial impact on welfare of a change in internal debt in period 0 is

$$
\begin{equation*}
\frac{d \Omega_{0}}{d b}=-\tau^{*} r \widetilde{K}+\left[F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right] \frac{d \tau^{*}}{d b} \tag{F.13}
\end{equation*}
$$

Evaluate (F.13) at $\beta=1$ using the the constant returns property $F=F_{K} K+F_{L} L^{m}$ :

$$
\begin{equation*}
\frac{d \Omega_{0}}{d b}(\beta=1)=-\tau^{*} r \widetilde{K}+\left[F_{K}\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b\right] \widetilde{K} \frac{d \tau^{*}}{d b}(\beta=1) \tag{F.14}
\end{equation*}
$$

We add and subtract $r C^{B \prime} \widetilde{K}$ from (F.14), and use (F.10) to simplify the resulting expression:

$$
\begin{align*}
\frac{d \Omega_{0}}{d b}(\beta=1) & =-\tau^{*} r \widetilde{K}-r C^{B^{\prime}} \widetilde{K}+r C^{B \prime} \widetilde{K}+\left(F_{K}-r b\right) \widetilde{K} \frac{d \tau^{*}}{d b}(\beta=1) \\
& =\widetilde{K}\left[r\left(C^{B^{\prime}}-\tau^{*}\right)+\left(F_{K}-r b\right) \frac{d \tau^{*}}{d b}(\beta=1)-r C^{B \prime}\right] \\
& =\widetilde{K}\left[\frac{\left(F_{K}-r b\right) \frac{d \widetilde{K}}{d b}(\beta=1)}{\frac{\partial \widetilde{K}}{\partial \tau}}-r C^{B^{\prime}}\right]<0, \quad \text { if } b=0 . \tag{F.15}
\end{align*}
$$

Equation (F.15) proves Equation (21) from Proposition 2. Following the same intuition as before, there exists some $\underline{\beta}^{2}<1$ such that (F.15) holds for $\beta \in\left[\underline{\beta}^{2}, 1\right]$. Equations (F.11) and (F.15) are simultaneously fulfilled for $\beta \in[\underline{\beta}, 1]$, where $\underline{\beta}=\max \left\{\underline{\beta}^{1}, \underline{\beta}^{2}\right\}$.

Lastly, both (F.6) and (F.13) are ambiguous for $\beta \overline{<} \underline{\beta}$ and $\left.\mu_{1} \bar{\in}\right]-\infty, 0[$.

## G Proof of Proposition 3

The government's maximization problem is

$$
\begin{equation*}
\max _{\tau, b} \int_{0}^{\infty} \Omega_{t} e^{-r t} d t \tag{G.1}
\end{equation*}
$$

The optimal tax rate is given by Equation (18), where $b$ is replaced by its optimal value $b^{*}$. The first-order condition with respect to $b$ is

$$
\begin{equation*}
\frac{\partial}{\partial b}=\int_{0}^{\infty}\left\{-\tau r K_{t}+\left[\tau\left(F_{K}-r b\right)+(1-\tau)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right] \frac{\partial w_{t}}{\partial K_{t}}\right] \frac{\partial K_{t}}{\partial b}\right\} e^{-r t} d t=0 \tag{G.2}
\end{equation*}
$$

where $\partial K_{t} / \partial b=\left(1-e^{\mu_{1} t}\right) \partial \widetilde{K} / \partial b$ and $\partial \widetilde{K} / \partial b$ is given by (E.15). We first prove that $0 \leq b^{*}<\hat{b}$. First, rewrite (E.15) as

$$
\begin{equation*}
\frac{\partial \widetilde{K}}{\partial b}=\frac{r\left(C^{B \prime}-\tau\right)\left(F_{L L}+G_{L L}\right)}{(1-\tau) F_{K K} G_{L L}}=\frac{r\left(C^{B \prime}-\tau\right)}{F_{K}-r b} \frac{\partial \widetilde{K}}{\partial \tau}>0 \tag{G.3}
\end{equation*}
$$

Moreover, the first-order condition with respect to $\tau$ is

$$
\begin{align*}
& \int_{0}^{\infty}\left[\left(F_{K}-r b\right) K_{t}+(1-\beta)\left[G\left(L_{t}^{d}\right)-w_{t} L_{t}^{d}\right]\right] e^{-r t} d t \\
& =-\int_{0}^{\infty}\left[\tau\left(F_{K}-r b\right)+(1-\tau)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right] \frac{\partial w_{t}}{\partial K_{t}}\right] \frac{\partial K_{t}}{\partial \tau} e^{-r t} d t . \tag{G.4}
\end{align*}
$$

Using (G.3) and (G.4) to evaluate (G.2), we get

$$
\begin{align*}
\frac{\partial}{\partial b} & =\int_{0}^{\infty}\left\{-\tau r K_{t}+\frac{r\left(C^{B \prime}-\tau\right)\left[\tau\left(F_{K}-r b\right)+(1-\tau)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right] \frac{\partial w_{t}}{\partial K_{t}}\right]}{F_{K}-r b} \frac{\partial K_{t}}{\partial \tau}\right\} e^{-r t} d t \\
& =\int_{0}^{\infty}\left\{-\tau r K_{t}-r\left(C^{B^{\prime}}-\tau\right) \frac{\left(F_{K}-r b\right) K_{t}+(1-\beta)\left[G\left(L_{t}^{d}\right)-w_{t} L_{t}^{d}\right]}{F_{K}-r b}\right\} e^{-r t} d t \\
& =r \int_{0}^{\infty}\left\{-C^{B \prime} K_{t}+\left(\tau-C^{B \prime}\right)(1-\beta) \frac{G\left(L_{t}^{d}\right)-w_{t} L_{t}^{d}}{F_{K}-r b}\right\} e^{-r t} d t . \tag{G.5}
\end{align*}
$$

Evaluated at $b=0$, (G.5) is strictly positive for $\beta<1$ and zero for $\beta=1$ (owing to $C^{B^{\prime}}(0)=0$ ). Thus, $b^{*}$ is strictly positive for $\beta<1$. Moreover, at $\beta=1$, (G.5) is strictly negative for $b>0$. Hence, $b^{*}=0$ for $\beta=1$. Next, evaluate (G.2) at $b=\hat{b}$. In this case, $C^{B^{\prime}}(\hat{b})=\tau$ and $\partial \widetilde{K} / \partial b=0$. Hence, the first-order condition (G.2) becomes

$$
\begin{equation*}
\frac{\partial}{\partial b}(b=\hat{b})=-\int_{0}^{\infty} \tau r K_{t} e^{-r t} d t<0 \tag{G.6}
\end{equation*}
$$

Hence, $b^{*}<\hat{b}$. This proves the first part of Proposition 3. To prove the second part, evaluate the integrand of (G.2) at $t=0$, taking into account $\partial K_{0} / \partial b=0$ :

$$
\begin{equation*}
\frac{\partial \Omega_{0}}{\partial b}=-\tau r K_{0}<0 \tag{G.7}
\end{equation*}
$$

Therefore, there is a negative welfare effect in period 0 . Because the change in welfare $\partial \Omega_{t} / \partial b$ is continuous in time, it is also negative for slightly positive values of $t$. Denote
the largest value of $t$ for which $\partial \Omega_{t} / \partial b$ is negative as $t^{*}$. Then, we must have

$$
\begin{equation*}
\int_{0}^{t^{*}} \frac{\partial \Omega_{t}}{\partial b} e^{-r t}<0 . \tag{G.8}
\end{equation*}
$$

## H Properties of the function $I_{t}\left(K_{t}, \tau_{t}\right)$

This section derives the first and second partial derivatives of the function $I_{t}\left(K_{t}, \tau_{t}\right)$. Start with $\partial I_{t} / \partial K_{t}$. First, we take the total differential of (B.4) with respect to $I_{t}$ and $K_{t}$, taking into account that $C^{\prime \prime}=c$, and rearrange to get

$$
\begin{equation*}
\frac{\partial I_{t}}{\partial K_{t}}=\frac{W_{K K}\left(K_{t}\right)}{c} \tag{H.1}
\end{equation*}
$$

It remains to derive $W_{K K}$. To do so, differentiate Equation (B.5) with respect to $K_{t}$, taking into account that $I_{t}$ and $L_{t}^{m}$ depend on $K_{t}$ :

$$
\begin{equation*}
r W_{K K}=\pi_{K K}^{M}+2 W_{K K} I_{t}+W_{K K K} I_{t} K_{t}+\left[\pi_{K I}^{M}+W_{K}+W_{K K} K\right] \frac{\partial I_{t}}{\partial K_{t}}, \tag{H.2}
\end{equation*}
$$

where

$$
\begin{align*}
\pi_{K K}^{M} & =\left(1-\tau_{t}\right)\left(F_{K K}+F_{K L} \frac{\partial L^{m}}{\partial K}\right)=\left(1-\tau_{t}\right) \frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}},  \tag{H.3a}\\
\pi_{K I}^{M} & =-\left(1+c I_{t}\right) . \tag{H.3b}
\end{align*}
$$

Using Equation (B.4) to express $W_{K}$, as well as (H.1), (H.3a) and (H.3b), Equation (H.2) becomes

$$
\begin{equation*}
r W_{K K}=\left(1-\tau_{t}\right) \frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}}+2 W_{K K} I_{t}+W_{K K K} I_{t} K_{t}+W_{K K} K \frac{W_{K K}}{c} . \tag{H.4}
\end{equation*}
$$

Equation (H.4) is quadratic in $W_{K K}$. To solve it, rewrite it first as

$$
\begin{equation*}
W_{K K}^{2}+\beta_{t} W_{K K}+\gamma_{t}=0, \tag{H.5}
\end{equation*}
$$

where

$$
\begin{equation*}
\beta_{t} \equiv \frac{c\left(2 I_{t}-r\right)}{K_{t}} \tag{H.6}
\end{equation*}
$$

$$
\begin{equation*}
\gamma_{t} \equiv \frac{c}{K_{t}}\left[\frac{\left(1-\tau_{t}\right) F_{K K} G_{L L}}{F_{L L}+G_{L L}}+W_{K K K} I_{t} K_{t}\right] . \tag{H.7}
\end{equation*}
$$

Now evaluate (H.5) around steady state, where $I_{t} \approx 0, K_{t} \approx \widetilde{K}$ and $\tau_{t} \approx \widetilde{\tau}$, and denote the corresponding parameters as $\widetilde{\beta}$ and $\widetilde{\gamma}$. We get

$$
\begin{align*}
\widetilde{\beta} & =-\frac{r c}{\widetilde{K}}<0  \tag{H.8}\\
\widetilde{\gamma} & =\frac{(1-\widetilde{\tau}) c F_{K K} G_{L L}}{\widetilde{K}\left(F_{L L}+G_{L L}\right)}<0 . \tag{H.9}
\end{align*}
$$

The two solutions to (H.5) are given by

$$
\begin{align*}
& W_{K K}=\frac{c}{2 \widetilde{K}}\left[r-\sqrt{r^{2}-\frac{4(1-\widetilde{\tau}) F_{K K} G_{L L} \widetilde{K}}{c\left(F_{L L}+G_{L L}\right)}}\right]=\frac{c \mu_{1}}{\widetilde{K}}<0,  \tag{H.10}\\
& W_{K K}=\frac{c}{2 \widetilde{K}}\left[r+\sqrt{r^{2}-\frac{4(1-\widetilde{\tau}) F_{K K} G_{L L} \widetilde{K}}{c\left(F_{L L}+G_{L L}\right)}}\right]=\frac{c \mu_{2}}{\widetilde{K}}>0, \tag{H.11}
\end{align*}
$$

where $\mu_{1}$ and $\mu_{2}$ are defined in Equation (C.9). Note that the value function $W(K)$ must be concave in the capital stock when the objective function as well as the rate of change of the capital stock $I_{t} K_{t}$ are concave in $K$ and $I$. Since this is satisfied, the solution to $W_{K K}$ is given by the negative root, (H.10). Thus, (H.1) and (H.10) together give

$$
\begin{equation*}
\frac{\partial I_{t}}{\partial K_{t}}=\frac{\mu_{1}}{\widetilde{K}}<0 \tag{H.12}
\end{equation*}
$$

Next, we derive the second derivative of investment with respect to capital. Differentiation of (H.1) with respect to $K_{t}$ gives

$$
\begin{equation*}
\frac{\partial^{2} I_{t}}{\partial K_{t}^{2}}=\frac{W_{K K K}\left(K_{t}\right)}{c} \tag{H.13}
\end{equation*}
$$

It remains to derive $W_{K K K}$. I follow Kimball (2014). To ease notation, define the right-hand side of (B.1) as $H_{t}$, i.e., $H_{t} \equiv \pi_{t}^{M}+W_{K}\left(K_{t}\right) I_{t} K_{t} .{ }^{2}$ Now, differentiate the Bellman equation $r W\left(K_{t}\right)=H_{t}$ with respect to capital without invoking the Envelope theorem:

$$
\begin{equation*}
r W_{K}=H_{K}+H_{I} \frac{\partial I_{t}}{\partial K_{t}} \tag{H.14}
\end{equation*}
$$

[^1]where
\[

$$
\begin{align*}
H_{K} & =\pi_{K}^{M}+W_{K} I_{t}+W_{K K} I_{t} K_{t}  \tag{H.15a}\\
H_{I} & =-\left(1+c I_{t}\right) K_{t}+W_{K} K_{t}=0, \tag{H.15b}
\end{align*}
$$
\]

where $H_{I}=0$ owing to the first-order condition (B.4). Next, differentiate (H.14) with respect to capital:

$$
\begin{equation*}
r W_{K K}=H_{K K}+2 H_{K I} \frac{\partial I_{t}}{\partial K_{t}}+H_{I I}\left(\frac{\partial I_{t}}{\partial K_{t}}\right)^{2}+H_{I} \frac{\partial^{2} I_{t}}{\partial K_{t}^{2}}, \tag{H.16}
\end{equation*}
$$

where

$$
\begin{align*}
H_{K K} & =\pi_{K K}^{M}+2 W_{K K} I_{t}+W_{K K K} I_{t} K_{t}  \tag{H.17a}\\
H_{K I} & =\pi_{K I}^{M}+W_{K}+W_{K K} K_{t}  \tag{H.17b}\\
H_{I I} & =-c K_{t} \tag{H.17c}
\end{align*}
$$

and $\pi_{K K}^{M}, \pi_{K I}^{M}$ are defined in (H.3a), (H.3b). Lastly, differentiate (H.16) with respect to $K_{t}$ :
$r W_{K K K}=H_{K K K}+3 H_{K K I} \frac{\partial I_{t}}{\partial K_{t}}+3 H_{I I K}\left(\frac{\partial I_{t}}{\partial K_{t}}\right)^{2}+3 \frac{\partial^{2} I_{t}}{\partial K_{t}^{2}}\left[H_{K I}+H_{I I} \frac{\partial I_{t}}{\partial K_{t}}\right]+H_{I} \frac{\partial^{3} I_{t}}{\partial K_{t}^{3}}$,
where

$$
\begin{align*}
H_{K K K} & =\pi_{K K K}^{M}+3 W_{K K K} I_{t}+W_{K K K K} I_{t} K_{t}  \tag{H.19a}\\
H_{K K I} & =2 W_{K K}+W_{K K K} K_{t}  \tag{H.19b}\\
H_{I I K} & =-c  \tag{H.19c}\\
\pi_{K K K}^{M} & =\left(1-\tau_{t}\right) \frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}} \frac{\xi_{t}}{K_{t}} \tag{H.19d}
\end{align*}
$$

The term $\xi_{t}$ is the value of $\xi$, defined in Equation (E.5), evaluated in period $t$. Moreover, according to (B.4), $H_{I}=0$. Additionally, Equation (H.1) gives

$$
H_{K I}+H_{I I} \frac{\partial I_{t}}{\partial K_{t}}=0
$$

Thus, (H.18) becomes

$$
\begin{equation*}
r W_{K K K}=H_{K K K}+3 H_{K K I} \frac{\partial I_{t}}{\partial K_{t}}+3 H_{I I K}\left(\frac{\partial I_{t}}{\partial K_{t}}\right)^{2} . \tag{H.20}
\end{equation*}
$$

Now, evaluate (H.20) around steady state, where $I_{t} \approx 0, K_{t} \approx \widetilde{K}, \tau_{t} \approx \widetilde{\tau}$, and using Equations(H.12), (H.10), (H.19a)-(H.19d). The resulting expression is

$$
\begin{equation*}
W_{K K K}=\frac{1}{r-3 \mu_{1}}\left[\frac{(1-\widetilde{\tau}) F_{K K} G_{L L} \xi}{\widetilde{K}\left(F_{L L}+G_{L L}\right)}+3 c\left(\frac{\mu_{1}}{\widetilde{K}}\right)^{2}\right] \tag{H.21}
\end{equation*}
$$

One way to simplify (H.21) is to solve (C.8) for the term containing the second derivatives of the production function. Inserting the resulting expression in (H.21), one gets

$$
\begin{equation*}
W_{K K K}=\frac{\mu_{1} c}{\left(r-3 \mu_{1}\right) \widetilde{K}^{2}}\left[\left(r-\mu_{1}\right) \xi+3 \mu_{1}\right] . \tag{H.22}
\end{equation*}
$$

Thus, (H.13) and (H.22) together give

$$
\begin{equation*}
\frac{\partial^{2} I_{t}}{\partial K_{t}^{2}}=\frac{\mu_{1}}{\left(r-3 \mu_{1}\right) \widetilde{K}^{2}}\left[\left(r-\mu_{1}\right) \xi+3 \mu_{1}\right] \tag{H.23}
\end{equation*}
$$

Next, use (H.1) to derive the cross-derivative

$$
\begin{equation*}
\frac{\partial^{2} I_{t}}{\partial K_{t} \partial \tau_{t}}=\frac{1}{c} \frac{\partial W_{K K}}{\partial \tau_{t}} \tag{H.24}
\end{equation*}
$$

where the effect of the statutory tax rate on the second derivative of the value function is determined by (H.5). A total differential of (H.5) gives

$$
\begin{equation*}
\frac{\partial W_{K K}}{\partial \tau_{t}}=-\frac{W_{K K} \frac{\partial \beta_{t}}{\partial \tau_{t}}+\frac{\partial \gamma_{t}}{\partial \tau_{t}}}{2 W_{K K}+\beta_{t}} . \tag{H.25}
\end{equation*}
$$

Using Equations (H.6) and (H.7), one can derive

$$
\begin{align*}
\frac{\partial \beta_{t}}{\partial \tau_{t}} & =2 \frac{c}{K_{t}} \frac{\partial I_{t}}{\partial \tau_{t}}  \tag{H.26}\\
\frac{\partial \gamma_{t}}{\partial \tau_{t}} & =\frac{c}{K_{t}}\left[-\frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}}+W_{K K K} K_{t} \frac{\partial I_{t}}{\partial \tau_{t}}\right] \tag{H.27}
\end{align*}
$$

In deriving the above expressions, we take into account that the capital stock $K_{t}$ does not react to changes in $\tau_{t}$, as it is a stock and cannot change immediately. Using (H.24)-(H.27), as well as (H.8) and (H.10), we get

$$
\begin{equation*}
\frac{\partial^{2} I_{t}}{\partial K_{t} \partial \tau_{t}}=\frac{1}{\left(r-2 \mu_{1}\right) c}\left[\frac{\partial I_{t}}{\partial \tau_{t}} \frac{\mu_{1} c}{\widetilde{K}}\left(2+\frac{\left(r-\mu_{1}\right) \xi+3 \mu_{1}}{\left(r-3 \mu_{1}\right) \widetilde{K}}\right)-\frac{F_{K K} G_{L L}}{F_{L L}+G_{L L}}\right] \tag{H.28}
\end{equation*}
$$

It remains to derive the first and second derivatives of investment with respect to the tax rate. To do so, differentiate totally (B.4) with respect to $I_{t}$ and $W_{K}$ to get

$$
\begin{equation*}
\partial I_{t}=\frac{1}{c} \partial W_{K} \tag{H.29}
\end{equation*}
$$

Then, rewrite (B.5) in the case of a time-varying tax rate as

$$
\begin{equation*}
\left(r-I_{t}\right) W_{K}=F_{K}-\tau_{t}\left(F_{K}-r b\right)-\left(I_{t}+C\left(I_{t}\right)\right)-C^{B}(r b)+W_{K K} I_{t} K_{t} \tag{H.30}
\end{equation*}
$$

Then, differentiate (H.30) with respect to $I_{t}, W_{K}, W_{K K}$ and $\tau_{t}$ :

$$
\begin{equation*}
\left(r-I_{t}\right) \partial W_{K}=-\left(F_{K}-r b\right) \partial \tau_{t}-\left(1+c I_{t}-W_{K}-W_{K K} K_{t}\right) \partial I_{t}+I_{t} K_{t} \partial W_{K K} \tag{H.31}
\end{equation*}
$$

We can use (H.29) and (H.31) to derive

$$
\begin{equation*}
\frac{\partial I_{t}}{\partial \tau_{t}}=\frac{-\left(F_{K}-r b\right)+I_{t} K_{t} \frac{\partial W_{K K}}{\partial \tau_{t}}}{r c+1-W_{K}-W_{K K} K_{t}} \tag{H.32}
\end{equation*}
$$

Around steady state, $I_{t} \approx 0, W_{K}=1+c \cdot 0, W_{K K}=\mu_{1} c / \widetilde{K}$. Thus, (H.32) simplifies to

$$
\begin{align*}
\frac{\partial I_{t}}{\partial \tau_{t}} & =-\frac{\left(F_{K}-r b\right)}{\left(r-\mu_{1}\right) c} \\
& =-\frac{\mu_{1}\left(F_{K}-r b\right)\left(F_{L L}+G_{L L}\right)}{(1-\widetilde{\tau}) F_{K K} G_{L L} \widetilde{K}}=-\frac{\mu_{1}}{\widetilde{K}} \frac{\partial \widetilde{K}}{\partial \tau}<0, \tag{H.33}
\end{align*}
$$

where the last row was derived by the use of (C.8) to substitute for $\left(r-\mu_{1}\right) c$. Lastly, derive the second derivative of investment with respect to the tax rate, by using (H.32). It is given by

$$
\begin{equation*}
\frac{\partial^{2} I_{t}}{\partial \tau_{t}^{2}}=\frac{\frac{\partial I_{t}}{\partial \tau_{t}}\left[2 K_{t} \frac{\partial W_{K K}}{\partial \tau_{t}}+\frac{\partial W_{K}}{\partial \tau_{t}}\right]}{r c+1-W_{K}-W_{K K} K_{t}} . \tag{H.34}
\end{equation*}
$$

Using Equations (H.25), (H.26), (H.27) and (H.33), the above equation can be expressed, around a steady state, as

$$
\begin{align*}
\frac{\partial^{2} I_{t}}{\partial \tau_{t}^{2}}= & -\frac{\left(F_{K}-r b\right)}{\left(r-\mu_{1}\right)^{2}\left(r-2 \mu_{1}\right) c} \times  \tag{H.35}\\
& \times\left[\frac{\partial I_{t}}{\partial \tau_{t}}\left(r+2 \mu_{1}+2 \mu_{1} \frac{\left(r-\mu_{1}\right) \xi+3 \mu_{1}}{\left(r-3 \mu_{1}\right)}\right)-\frac{2 \widetilde{K} F_{K K} G_{L L}}{c\left(F_{L L}+G_{L L}\right)}\right]
\end{align*}
$$

## I Proof of Proposition 4

To derive the optimal tax rate, note first that period $t$ welfare is given by

$$
\begin{align*}
\Omega_{t}= & \tau_{t}\left[F\left(K_{t}, L_{t}^{m}\left(K_{t}\right)\right)-r b K_{t}\right]+\left(1-\tau_{t}\right) w_{t}\left(K_{t}\right) L_{t}^{m}\left(K_{t}\right)+G\left(L_{t}^{d}\left(K_{t}\right)\right) \\
& -\left(1-\tau_{t}\right)(1-\beta)\left[G\left(L_{t}^{d}\left(K_{t}\right)\right)-w_{t}\left(K_{t}\right) L_{t}^{d}\left(K_{t}\right)\right] \tag{I.1}
\end{align*}
$$

Denote the government's value function as $U\left(K_{t}\right)$. Then, its maximization problem can be written as

$$
\begin{equation*}
r U\left(K_{t}\right)=\max _{\tau_{t}}\left\{\Omega_{t}+U_{K}\left(K_{t}\right) I_{t} K_{t}\right\} \tag{I.2}
\end{equation*}
$$

To simplify the exposition of the proof, use the notation $A\left(K_{t}, \tau_{t}\right) \equiv I_{t} K_{t}$ and $H^{G} \equiv$ $\Omega_{t}+U_{K}\left(K_{t}\right) A\left(K_{t}, \tau_{t}\right)$, where $H^{G}$ can be referred to as the prevalue function of the government. Since $\Omega_{t}$ in linear in the tax rate $\tau_{t}$, we need to assume that $A\left(K_{t}, \tau_{t}\right)$ is strictly concave in the tax rate for the maximization problem to be well-behaved. Thus, we require $A_{\tau \tau}=\left(\partial^{2} I_{t} / \partial \tau_{t}^{2}\right) K_{t}<0$, where $\partial^{2} I_{t} / \partial \tau_{t}^{2}$ is given by (H.35). The first-order condition of the government is given by

$$
\begin{align*}
H_{\tau}^{G}= & F\left(K_{t}, L_{t}^{m}\left(K_{t}\right)\right)-r b K_{t}-w_{t}\left(K_{t}\right) L_{t}^{m}\left(K_{t}\right)+(1-\beta)\left[G\left(L_{t}^{d}\left(K_{t}\right)\right)-w_{t}\left(K_{t}\right) L_{t}^{d}\left(K_{t}\right)\right] \\
& +U_{K}\left(K_{t}\right) A_{\tau}=0, \tag{I.3}
\end{align*}
$$

where $A_{\tau}=\left(\partial I_{t} / \partial \tau_{t}\right) K_{t}$. We derive first the steady state tax rate $\widetilde{\tau}$. To find it, one needs first the value of $U_{K}\left(K_{t}\right)$, evaluated in steady state. It is found by a differentiation of the maximized Bellman equation with respect to capital:

$$
\begin{equation*}
r U_{K}=\Omega_{K}+U_{K K} A+U_{K} A_{K} \tag{I.4}
\end{equation*}
$$

where

$$
\begin{align*}
\Omega_{K}= & \tau_{t}\left(F_{K}-r b+F_{L} \frac{\partial L_{t}^{m}}{\partial K_{t}}\right)+\left(1-\tau_{t}\right) w_{t} \frac{\partial L_{t}^{m}}{\partial K_{t}}+G_{L} \frac{\partial L_{t}^{d}}{\partial K_{t}} \\
& -(1-\beta)\left(1-\tau_{t}\right)\left(G_{L}-w_{t}\right) \frac{\partial L_{t}^{d}}{\partial K_{t}}+\frac{\partial w_{t}}{\partial K_{t}}\left(1-\tau_{t}\right)\left(L_{t}^{m}+(1-\beta) L_{t}^{d}\right) \\
= & \tau_{t}\left(F_{K}-r b\right)+\frac{\partial w_{t}}{\partial K_{t}}\left(1-\tau_{t}\right)\left(L_{t}^{m}+(1-\beta) L_{t}^{d}\right)  \tag{I.5}\\
A_{K}= & I_{t}+\frac{\partial I_{t}}{\partial K_{t}} K_{t} \tag{I.6}
\end{align*}
$$

Around steady state, $K_{t} \approx \widetilde{K}, I_{t} \approx 0$ and $\partial I_{t} / \partial K_{t}$ is given by (H.12). Thus, one can solve (I.4) for $U_{K}$ :

$$
\begin{equation*}
U_{K}(\widetilde{K})=\frac{\widetilde{\tau}\left(F_{K}-r b\right)+(1-\widetilde{\tau}) \frac{\partial \widetilde{w}}{\partial K}\left(\widetilde{L}^{m}+(1-\beta) \widetilde{L}^{d}\right)}{r-\mu_{1}} \tag{I.7}
\end{equation*}
$$

Moreover, one can evaluate (I.3) around steady state, using (H.33) and (I.7). The resulting expression is (18), where one substitutes $\tau^{*}$ with $\widetilde{\tau}$. Hence, $\widetilde{\tau}$ is equal to $\tau^{*}$ from Section 3.

To derive the path of the optimal tax rate, totally differentiate (I.3) with respect to time, taking into account that both $\tau_{t}$ and $K_{t}$ are functions of time. The resulting expression is

$$
\begin{equation*}
H_{\tau \tau}^{G} \dot{\tau}_{t}+H_{\tau K}^{G} \dot{K}_{t}=0 \tag{I.8}
\end{equation*}
$$

where

$$
\begin{align*}
H_{\tau \tau}^{G} & =U_{K} A_{\tau \tau}<0,  \tag{I.9}\\
H_{\tau K}^{G} & =\Omega_{\tau K}+U_{K K} A_{\tau}+U_{K} A_{\tau K},  \tag{I.10}\\
\Omega_{\tau K} & =F_{K}-r b+F_{L} \frac{\partial L_{t}^{m}}{\partial K_{t}}-w_{t} \frac{\partial L_{t}^{m}}{\partial K_{t}}+(1-\beta)\left(G_{L}-w_{t}\right) \frac{\partial L_{t}^{d}}{\partial K_{t}}-\frac{\partial w_{t}}{\partial K_{t}}\left(L_{t}^{m}+(1-\beta) L_{t}^{d}\right) \\
& =F_{K}-r b-\frac{\partial w_{t}}{\partial K_{t}}\left(L_{t}^{m}+(1-\beta) L_{t}^{d}\right)  \tag{I.11}\\
A_{\tau K} & =\frac{\partial I_{t}}{\partial \tau_{t}}+\frac{\partial^{2} I_{t}}{\partial \tau_{t} \partial K_{t}} K_{t} . \tag{I.12}
\end{align*}
$$

The expression (I.9) is negative due to our assumption about the concavity of the objective function. One can solve (I.8) for $\tau_{t}$. Near steady state $\dot{K}_{t}$ can be approximated (using (4) and (H.12)) as

$$
\begin{align*}
\dot{K}_{t}=I_{t}\left(K_{t}\right) K_{t} & \approx\left[\frac{\partial I_{t}}{\partial K_{t}} K_{t}+I_{t}\right]\left(K_{t}-\widetilde{K}\right) \\
& \approx \mu_{1}\left(K_{t}-\widetilde{K}\right) \tag{I.13}
\end{align*}
$$

where in the second row of (I.13) we used the steady state conditions $K_{t} \approx \widetilde{K}, I_{t} \approx \widetilde{I}=0$ and Equation (H.12). Starting from an initial capital stock $K_{0}$, the solution to the differential equation (I.13) is

$$
\begin{equation*}
K_{t}-\widetilde{K}=\left(K_{0}-\widetilde{K}\right) e^{\mu_{1} t} \tag{I.14}
\end{equation*}
$$

Thus, one can rewrite (I.8) as

$$
\begin{equation*}
\dot{\tau}_{t}=-\frac{H_{\tau K}^{G}}{H_{\tau \tau}^{G}} \mu_{1}\left(K_{0}-\widetilde{K}\right) e^{\mu_{1} t} \tag{I.15}
\end{equation*}
$$

Around a steady state, both $H_{\tau K}^{G}$ and $H_{\tau \tau}^{G}$ are constant and can be denoted as $\widetilde{H}_{\tau K}^{G}, \widetilde{H}_{\tau \tau}^{G}$. Thus, (I.15) can be solved by integration (using the terminal condition $\tau_{\infty}=\widetilde{\tau}$ ) to get

$$
\begin{equation*}
\tau_{t}=\widetilde{\tau}+\alpha\left(K_{0}-\widetilde{K}\right) e^{\mu_{1} t} \tag{I.16}
\end{equation*}
$$

where

$$
\begin{equation*}
\alpha \equiv-\frac{\widetilde{H}_{\tau K}^{G}}{\widetilde{H}_{\tau \tau}^{G}} \tag{I.17}
\end{equation*}
$$

Note additionally that the impact of the capital stock in period $t$ on the period $t$ tax rate can be derived from (I.8), when one multiplies (I.8) by $\partial t$ and solves for $\partial \tau_{t} / \partial K_{t}$ :

$$
\begin{equation*}
\frac{\partial \tau_{t}}{\partial K_{t}}=-\frac{H_{\tau K}^{G}}{H_{\tau \tau}^{G}} \tag{I.18}
\end{equation*}
$$

Thus, $\alpha$ determines the slope of the function $\tau(K)$ around the steady state, i.e., $\alpha \equiv$ $\partial \widetilde{\tau} / \partial K$. Due to $H_{\tau \tau}^{G}<0$, the sign of $\alpha$ is determined by the sign of $H_{\tau K}^{G}$, which may be either positive or negative (see (I.10)). Hence, the optimal tax rate may either be an increasing or a decreasing function of the capital stock.

## J Proof of Proposition 5

Proposition 5 states that Proposition 1 holds in the case of a time-varying tax rate when one replaces $\tau^{*}$ by $\widetilde{\tau}$. The proof is straightforward. First, $\tau^{*}$ and $\widetilde{\tau}$ coincide (see Proposition 4). Moreover, $\widetilde{K}$ is determined by (10a) in both situations. Hence, Proposition 1 can be proven again using Equations (10a) and (18).

Second, Proposition 5 states that Proposition 2 is qualitatively unchanged. Because $\tau^{*}=\widetilde{\tau}$, all long term effects of a change in internal debt remain exactly the same as in Proposition 2. Moreover, if the economy is static ( $\mu_{1} \rightarrow-\infty$ ), the time-varying tax rate model collapses to a static model with a constant tax rate. Hence, Lemma 2 holds as well. Therefore, it remains to prove that Equation (21) holds. To derive the initial impact of $b$ on welfare, differentiate Equation (F.12) with respect to $b$ :

$$
\begin{equation*}
\frac{d \Omega_{0}}{d b}=-\tau_{0} r \widetilde{K}+\left[F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left(G\left(\widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right)\right] \frac{d \tau_{0}}{d b} \tag{J.1}
\end{equation*}
$$

where $\tau_{0}$ is the steady state tax rate $\widetilde{\tau}$ associated with the initial steady state capital stock $K_{0}=\widetilde{K}$. Evaluate (J.1) at $\beta=1$ and use the the constant returns property $F=F_{K} K+F_{L} L^{m}:$

$$
\begin{equation*}
\frac{d \Omega_{0}}{d b}(\beta=1)=-\widetilde{\tau} r \widetilde{K}+\left[F_{K}\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b\right] \widetilde{K} \frac{d \tau_{0}}{d b}(\beta=1) \tag{J.2}
\end{equation*}
$$

The change in the initial tax rate is, according to Equation (25):

$$
\begin{equation*}
\frac{d \tau_{0}}{d b}=\frac{d \widetilde{\tau}}{d b}-\alpha \frac{d \widetilde{K}}{d b} \tag{J.3}
\end{equation*}
$$

We add and subtract $r C^{B \prime} \widetilde{K}$ from (J.2), and use (J.3) to simplify the resulting expression:

$$
\begin{align*}
\frac{d \Omega_{0}}{d b}(\beta=1) & =-\widetilde{\tau} r \widetilde{K}-r C^{B^{\prime}} \widetilde{K}+r C^{B^{\prime}} \widetilde{K}+\left(F_{K}-r b\right) \widetilde{K}\left[\frac{d \widetilde{\tau}}{d b}(\beta=1)-\alpha \frac{d \widetilde{K}}{d b}(\beta=1)\right] \\
& =\widetilde{K}\left[\left(F_{K}-r b\right)\left(\frac{r\left(C^{B \prime}-\widetilde{\tau}\right)}{F_{K}-r b}+\frac{d \widetilde{\tau}}{d b}(\beta=1)-\alpha \frac{d \widetilde{K}}{d b}(\beta=1)\right)-r C^{B \prime}\right] \\
& =\widetilde{K}\left[\frac{\left(F_{K}-r b\right) \frac{d \widetilde{K}}{d b}(\beta=1)}{\frac{\partial \widetilde{K}}{\partial \tau}}\left(1-\frac{\partial \widetilde{K}}{\partial \tau} \frac{\partial \widetilde{\tau}}{\partial K}\right)-r C^{B^{\prime}}\right]<0, \quad \text { if } \quad \frac{\partial \widetilde{K}}{\partial \tau} \frac{\partial \widetilde{\tau}}{\partial K}<1, b=0, \tag{J.4}
\end{align*}
$$

where I used (F.10) to derive the last row of (J.4) and replaced $\alpha$ by $\partial \widetilde{\tau} / \partial K$. Equation (10a) determines the steady state capital stock as a function of the tax rate (and, thus, $\partial \widetilde{K} / \partial \tau$ ), while (I.18) determines the optimal tax rate as a function of the capital stock (and, thus, $\partial \widetilde{\tau} / \partial K)$. The steady state is stable if the product of the slopes of these functions is less than one, i.e., if $(\partial \widetilde{K} / \partial \tau)(\partial \widetilde{\tau} / \partial K)<1$. Thus, Proposition 2 holds in the case of a time-varying tax rate when the steady state is stable.

The initial negative welfare impact, determined by (J.4), is more (less) pronounced than in the case of a constant tax rate if $\partial \widetilde{\tau} / \partial K$ is positive (negative).

Lastly, we derive the optimal TCR, similarly to Appendix G. The first-order condition with respect to $b$ is given by (G.2), when one replaces $\tau$ by $\tau_{t}$ in the integrand. Hence, we can derive the optimal $b^{*}$ analogously. The only difference is that we must replace (G.4) by the following equation, derived from (I.3)-(I.6):

$$
\begin{align*}
& \tau_{t}\left(F_{K}-r b\right)+\frac{\partial w_{t}}{\partial K_{t}}\left(1-\tau_{t}\right)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right]  \tag{J.5}\\
& =-\frac{r-I_{t}-\frac{\partial I_{t}}{\partial K_{t}} K_{t}}{\frac{\partial I_{t}}{\partial \tau_{t}} K_{t}}\left[F\left(K_{t}, L_{t}^{m}\right)-r b K_{t}-w_{t} L_{t}^{m}+(1-\beta)\left[G\left(L_{t}^{d}-w_{t} L_{t}^{d}\right)\right]\right]-U_{K K} I_{t} K_{t} .
\end{align*}
$$

Inserting (J.5) in the first-order condition with respect to $b$, evaluating at $b=0$, and then evaluating it around the steady state, gives the same result as (G.5). Thus, the optimal TCR is positive. Following the remaining steps from Appendix G, we can prove that that $0<b^{*}<\hat{b}$ and that (23) holds.

## K Model with endogenous domestic capital

Denote the domestic firm's value function, evaluated at period 0 as $V_{0}^{D}$. It can be derived similarly to the MNE's $V_{0}$ in Appendix A. Following the same steps, it is straightforward to show that

$$
\begin{equation*}
V_{0}^{D}=\int_{0}^{\infty} \pi_{t}^{D} e^{-r t} d t \tag{K.1}
\end{equation*}
$$

where $\pi_{t}^{D}$ is defined in Equation (26). The domestic firm chooses $L_{t}^{d}$ and $I_{t}^{d}$ to maximize (K.1) subject to the equation of motion (27). Following the same steps as in Appendix B, the optimal labor demand $L_{t}^{d}$ is again determined by Equation (2), while investment $I_{t}^{d}$ follows

$$
\begin{equation*}
\dot{I}_{t}^{d}=\frac{1}{C^{d \prime}}\left[r+C^{d}\left(I_{t}^{d}\right)+C^{d \prime}\left(I_{t}^{d}\right)\left(r-I_{t}^{d}\right)-G_{K}\left(K_{t}^{d}, L_{t}^{d}\right)(1-\tau)\right] . \tag{K.2}
\end{equation*}
$$

Next, Equations (2), (8), and (9) determine the labor inputs $L_{t}^{d}, L_{t}^{m}$ and wage rate $w_{t}$ as implicit functions of the two capital stocks, $K_{t}, K_{t}^{d}$. That is, we have $L_{t}^{m}\left(K_{t}, K_{t}^{d}\right)$, $L_{t}^{d}\left(K_{t}, K_{t}^{d}\right), w_{t}\left(K_{t}, K_{t}^{d}\right)$. The partial derivatives with respect to $K_{t}$ are again given by (11) in the main text. The partial derivatives with respect to $K_{t}^{d}$ are derived analogously to (11) and are given by

$$
\begin{equation*}
\frac{\partial L_{t}^{m}}{\partial K_{t}^{d}}=\frac{G_{L K}}{F_{L L}+G_{L L}}<0, \quad \frac{\partial L_{t}^{d}}{\partial K_{t}^{d}}=-\frac{\partial L_{t}^{m}}{\partial K_{t}}, \quad \frac{\partial w_{t}}{\partial K_{t}^{d}}=\frac{F_{L L} G_{L K}}{F_{L L}+G_{L L}}>0 . \tag{K.3}
\end{equation*}
$$

Next, we derive the impact of changes in the tax rate $\tau$ and the TCR $b$ on the two capital stocks, labor demands, and wage rate (analogously to Lemma 1). First, let us derive the steady state effects. The steady state capital stock $\widetilde{K}$ is determined by (10a), while $\widetilde{K}^{d}$ is detremined by (28) (i.e., the solution to (K.2) in steady state). Moreover, the steady state labor demands and wage rate are determined by (10b) and (10c). Solve (10c) for $\widetilde{L}^{d}$ and insert the solution in $G_{L}\left(\widetilde{K}^{d}, \widetilde{L}^{d}\right)=\widetilde{w}$. Totally differentiating (10a),
the two equations in (10b), and (28) with respect to $\widetilde{K}, \widetilde{L}^{m}, \widetilde{K}^{d}, \widetilde{w}, \tau$, and $b$ we get

$$
\underbrace{\left(\begin{array}{cccc}
F_{K K} & F_{K L} & 0 & 0  \tag{K.4}\\
F_{L K} & F_{L L} & 0 & -1 \\
0 & -G_{K L} & G_{K K} & 0 \\
0 & -G_{L L} & G_{L K} & -1
\end{array}\right)}_{=J_{2}}\left(\begin{array}{c}
\partial \widetilde{K} \\
\partial \widetilde{L}^{m} \\
\partial \widetilde{K}^{d} \\
\partial \widetilde{w}
\end{array}\right)=\left(\begin{array}{cc}
\frac{F_{K}-r b}{1-\tau} & \frac{r\left(C^{\left.B^{\prime}-\tau\right)}\right.}{1-\tau} \\
0 & 0 \\
\frac{G_{K}}{1-\tau} & 0 \\
0 & 0
\end{array}\right)\binom{\partial \tau}{\partial b} .
$$

The determinant of $J_{2}$ is

$$
\begin{equation*}
\left|J_{2}\right|=-\left[G_{K K}\left(F_{K K} F_{L L}-F_{K L}^{2}\right)+F_{K K}\left(G_{K K} G_{L L}-G_{K L}^{2}\right)\right]>0, \tag{K.5}
\end{equation*}
$$

where the positive sign is due to the assumption that at least one production function is characterized by decreasing returns to scale. Applying Cramer's rule to (K.4), we get

$$
\begin{align*}
\frac{\partial \widetilde{K}}{\partial \tau} & =\frac{-\left(F_{K}-r b\right)\left[G_{K K}\left(F_{L L}+G_{L L}\right)-G_{K L}^{2}\right]+G_{K} F_{K L} G_{K L}}{(1-\tau)\left|J_{2}\right|}  \tag{K.6}\\
\frac{\partial \widetilde{L}^{m}}{\partial \tau} & =\frac{\left(F_{K}-r b\right) F_{K L} G_{K K}-G_{K} F_{K K} G_{K L}}{(1-\tau)\left|J_{2}\right|}  \tag{K.7}\\
\frac{\partial \widetilde{K}^{d}}{\partial \tau} & =\frac{\left(F_{K}-r b\right) F_{K L} G_{K L}-G_{K}\left[F_{K K}\left(F_{L L}+G_{L L}\right)-F_{K L}^{2}\right]}{(1-\tau)\left|J_{2}\right|}  \tag{K.8}\\
\frac{\partial \widetilde{w}}{\partial \tau} & =-\frac{\left(F_{K}-r b\right) F_{K L}\left[G_{K K} G_{L L}-G_{K L}^{2}\right]+G_{K} G_{K L}\left[F_{K K} F_{L L}-F_{K L}^{2}\right]}{(1-\tau)\left|J_{2}\right|}<0,  \tag{K.9}\\
\frac{\partial \widetilde{K}}{\partial b} & =\frac{-r\left(C^{B \prime}-\tau\right)\left[G_{K K}\left(F_{L L}+G_{L L}\right)-G_{K L}^{2}\right]}{(1-\tau)\left|J_{2}\right|}>0, \text { if } b<\hat{b},  \tag{K.10}\\
\frac{\partial \widetilde{L}^{m}}{\partial b} & =\frac{r\left(C^{B \prime}-\tau\right) F_{K L} G_{K K}}{(1-\tau)\left|J_{2}\right|}>0, \text { if } b<\hat{b},  \tag{K.11}\\
\frac{\partial \widetilde{K}^{d}}{\partial b} & =\frac{r\left(C^{B \prime}-\tau\right) F_{K L} G_{K L}}{(1-\tau)\left|J_{2}\right|}<0, \text { if } b<\hat{b},  \tag{K.12}\\
\frac{\partial \widetilde{w}}{\partial b} & =\frac{-r\left(C^{B \prime}-\tau\right) F_{K L}\left[G_{K K} G_{L L}-G_{K L}^{2}\right]}{(1-\tau)\left|J_{2}\right|}>0, \text { if } b<\hat{b} . \tag{K.13}
\end{align*}
$$

One important result is that a relaxation of the TCR lowers the domestic capital stock in the long term. The reason is that it stimulates investment by the MNE, which raises the MNE's labor demand and, hence, the wage rate. At a higher wage, the domestic firm lowers its own labor demand and therefore its optimal capital stock also declines.

Next, we derive the transitional dynamics of the capital stocks, following a change in one of the policy parameters. Consider first a change in the tax rate $\tau$. The transition is determined by four differential equations: (4), (7), (27), and (K.2). I follow Wildasin (2011) in solving the system of differential equations. First, define the following change
of variables:

$$
\begin{align*}
y_{1} \equiv \frac{\partial K_{t}}{\partial \tau}, & y_{2} \equiv \frac{\partial K_{t}^{d}}{\partial \tau}  \tag{K.14}\\
x_{1} \equiv \frac{\partial \dot{K}_{t}}{\partial \tau}, & x_{2} \equiv \frac{\partial \dot{K}_{t}^{d}}{\partial \tau} \tag{K.15}
\end{align*}
$$

Then, $x_{i}=\dot{y_{i}}$ for $i=1,2$. Now, differentiate (4), (7), (27), and (K.2) with respect to $K_{t}, \dot{K}_{t}, I_{t}, \dot{I}_{t}, K_{t}^{d}, \dot{K}_{t}^{d}, I_{t}^{d}, \dot{I}_{t}^{d}$, and $\tau$. Following the same steps as in Equations (C.2)-(C.6) in Appendix C, and using the definitions from (K.14)-(K.15), we get

$$
\begin{align*}
& \dot{x}_{1}-r x_{1}-a_{11} y_{1}-a_{12} y_{2}=\Gamma_{1}  \tag{K.16}\\
& \dot{x}_{2}-r x_{2}-a_{21} y_{1}-a_{22} y_{2}=\Gamma_{2} \tag{K.17}
\end{align*}
$$

where

$$
\begin{align*}
a_{11} & \equiv-\frac{(1-\tau) \widetilde{K}}{C^{\prime \prime}} \frac{F_{K K}\left(F_{L L}+G_{L L}\right)-F_{K L}^{2}}{F_{L L}+G_{L L}}  \tag{K.18}\\
a_{12} & \equiv-\frac{(1-\tau) \widetilde{K}}{C^{\prime \prime}} \frac{F_{K L} G_{K L}}{F_{L L}+G_{L L}},  \tag{K.19}\\
a_{21} & \equiv-\frac{(1-\tau) \widetilde{K}^{d}}{C^{d \prime \prime}} \frac{F_{K L} G_{K L}}{F_{L L}+G_{L L}}  \tag{K.20}\\
a_{22} & \equiv-\frac{(1-\tau) \widetilde{K}^{d}}{C^{d \prime \prime}} \frac{G_{K K}\left(F_{L L}+G_{L L}\right)-G_{K L}^{2}}{F_{L L}+G_{L L}},  \tag{K.21}\\
\Gamma_{1} & \equiv \frac{\left(F_{K}-r b\right) \widetilde{K}}{C^{\prime \prime}}  \tag{K.22}\\
\Gamma_{2} & \equiv \frac{G_{K} \widetilde{K}^{d}}{C^{d \prime \prime}} \tag{K.23}
\end{align*}
$$

The system of four differential equations (K.16),(K.17), $\dot{y}_{1}=x_{1}$, and $\dot{y}_{2}=x_{2}$ is qualitatively identical to the system solved by Wildasin (2011) (presented by Equation (A.10) in his paper). The solution is also identical. The homogeneous part has two positive and two negative roots (see Wildasin (2011), Appendix A for a proof). The two negative roots are given by

$$
\begin{equation*}
\zeta_{1}=\frac{r-\sqrt{b_{1}+2 \sqrt{b_{2}}}}{2}, \quad \zeta_{2}=\frac{r-\sqrt{b_{1}-2 \sqrt{b_{2}}}}{2} \tag{K.24}
\end{equation*}
$$

where

$$
\begin{array}{r}
b_{1}=r^{2}+2\left(a_{11}+a_{22}\right), \\
b_{2}=\left(a_{22}-a_{11}\right)^{2}+4 a_{12} a_{21} . \tag{K.26}
\end{array}
$$

The stable general solutions for $y_{1} \equiv \frac{\partial K_{t}}{\partial \tau}$ and $y_{2} \equiv \frac{\partial K_{t}^{d}}{\partial \tau}$ are given by (Turnovsky, 1997, p. 259):

$$
\begin{align*}
\frac{\partial K_{t}}{\partial \tau} & =\frac{\partial \widetilde{K}}{\partial \tau}+B_{1 \tau} e^{\zeta_{1} t}+B_{2 \tau} e^{\zeta_{2} t}  \tag{K.27}\\
\frac{\partial K_{t}^{d}}{\partial \tau} & =\frac{\partial \widetilde{K}^{d}}{\partial \tau}+B_{1 \tau} \psi_{21} e^{\zeta_{1} t}+B_{2 \tau} \psi_{22} e^{\zeta_{2} t} \tag{K.28}
\end{align*}
$$

where $B_{1 \tau}, B_{2 \tau}$ are constants to be determined by the initial conditions and $\psi_{2 i}$ are determined by the homogeneous solution as follows:

$$
\left(\begin{array}{cccc}
-\zeta_{i} & 0 & 1 & 0  \tag{K.29}\\
0 & -\zeta_{i} & 0 & 1 \\
a_{11} & a_{12} & r-\zeta_{i} & 0 \\
a_{21} & a_{22} & 0 & r-\zeta_{i}
\end{array}\right)\left(\begin{array}{c}
1 \\
\psi_{2 i} \\
\psi_{3 i} \\
\psi_{4 i}
\end{array}\right)=0
$$

Solving (K.29) for $\psi_{2 i}$, we get

$$
\begin{equation*}
\psi_{2 i}=-\frac{\left(r-\zeta_{i}\right) \zeta_{i}+a_{11}}{a_{12}}, \quad i=1,2 \tag{K.30}
\end{equation*}
$$

Moreover, the constants $B_{1 \tau}$ and $B_{2 \tau}$ are determined by the initial conditions $\partial K_{0} / \partial \tau=$ 0 and $\partial K_{0}^{d} / \partial \tau=0$. Together (K.27),(K.28), and the initial conditions determine

$$
\begin{align*}
& B_{1 \tau}=\frac{-\frac{\partial \widetilde{K}^{d}}{\partial \tau}+\psi_{22} \frac{\partial \widetilde{K}}{\partial \tau}}{\psi_{21}-\psi_{22}}  \tag{K.31}\\
& B_{2 \tau}=\frac{\frac{\partial \widetilde{K}^{d}}{\partial \tau}-\psi_{21} \frac{\partial \widetilde{K}}{\partial \tau}}{\psi_{21}-\psi_{22}} \tag{K.32}
\end{align*}
$$

Furthermore, the impact of the TCR $b$ on $K_{t}, K_{t}^{d}$ can be derived analogously to the effect of $\tau$.

Next, I determine the optimal tax $\tau^{*}$ and TCR $b^{*}$. The maximization problem is analogous to (G.1) in Appendix G. The first-order condition with respect to $\tau$ is, after some cancellation of terms including the changes in labor demands,

$$
\begin{aligned}
\frac{\partial}{\partial \tau} & =\int_{0}^{\infty}\left\{F\left(K_{t}, L_{t}^{m}\right)-r b K_{t}-w_{t} L_{t}^{m}+(1-\beta)\left[G\left(K_{t}^{d}, L_{t}^{d}\right)-w_{t} L_{t}^{d}\right]\right. \\
& +\left[\tau\left(F_{K}-r b\right)+(1-\tau)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right] \frac{\partial w_{t}}{\partial K_{t}}\right] \frac{\partial K_{t}}{\partial \tau} \\
& +\left[\tau G_{K}+(1-\tau)\left[L_{t}^{m}+(1-\beta) L_{t}^{d}\right] \frac{\partial w_{t}}{\partial K_{t}^{d}}\right] \frac{\partial K_{t}^{d}}{\partial \tau}
\end{aligned}
$$

$$
\begin{equation*}
\left.-\beta\left[\left(I_{t}^{d}+C^{d}\left(I_{t}^{d}\right)-(1-\tau) G_{K}\right) \frac{\partial K_{t}^{d}}{\partial \tau}+\left(1+C^{d \prime}\right) K_{t}^{d} \frac{\partial I_{t}^{d}}{\partial \tau}\right]\right\} e^{-r t} d t=0 \tag{K.33}
\end{equation*}
$$

Next, we evaluate (K.33) around steady state. In steady state, $I_{t}^{d} \approx \widetilde{I}^{d}=0$ and thus $C^{d}\left(I_{t}^{d}\right) \approx 0$. Also, from (27), evaluated around steady state, we have $K_{t}^{d} \partial I_{t}^{d} / \partial \tau \approx$ $\partial \dot{K}_{t}^{d} / \partial \tau$. Furthermore, from the domestic firm's maximization problem, around steady state, we get $1+C^{d \prime} \approx(1-\tau) G_{K} / r$. Thus, (K.33) becomes

$$
\begin{align*}
\frac{\partial}{\partial \tau} & =\int_{0}^{\infty}\left\{F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left[G\left(\widetilde{K}^{d}, \widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right]\right. \\
& +\left[\tau^{*}\left(F_{K}-r b\right)+(1-\tau)\left[\widetilde{L}^{m}+(1-\beta) \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \widetilde{K}}\right] \frac{\partial K_{t}}{\partial \tau} \\
& +\left[\tau G_{K}+(1-\tau)\left[\widetilde{L}^{m}+(1-\beta) \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \widetilde{K}^{d}}\right] \frac{\partial K_{t}^{d}}{\partial \tau} \\
& \left.+\beta(1-\tau) G_{K}\left[\frac{\partial K_{t}^{d}}{\partial \tau}-\frac{1}{r} \frac{\partial \dot{K}_{t}^{d}}{\partial \tau}\right]\right\} e^{-r t} d t=0 . \tag{K.34}
\end{align*}
$$

Integration of the last row of (K.34) by parts shows that it equals zero. Thus, only the first three rows of (K.34) remain. Next, it is straightforward to use (K.27) and (K.28) to integrate (K.34). Simplifying the resulting equation by expressing $L^{m}$ as $1-L^{d}$, we get

$$
\begin{align*}
0 & =F\left(\widetilde{K}, \widetilde{L}^{m}\right)-r b \widetilde{K}-\widetilde{w} \widetilde{L}^{m}+(1-\beta)\left[G\left(\widetilde{K}^{d}, \widetilde{L}^{d}\right)-\widetilde{w} \widetilde{L}^{d}\right] \\
& +\left[\tau^{*}\left(F_{K}-r b\right)+\left(1-\tau^{*}\right)\left[1-\beta \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \widetilde{K}}\right]\left(\frac{\partial \widetilde{K}}{\partial \tau}+\frac{r B_{1 \tau}}{r-\zeta_{1}}+\frac{r B_{2 \tau}}{r-\zeta_{2}}\right) \\
& +\left[\tau^{*} G_{K}+\left(1-\tau^{*}\right)\left[1-\beta \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \widetilde{K}^{d}}\right]\left(\frac{\partial \widetilde{K}^{d}}{\partial \tau}+\frac{r B_{1 \tau} \psi_{21}}{r-\zeta_{1}}+\frac{r B_{2 \tau} \psi_{22}}{r-\zeta_{2}}\right) . \tag{K.35}
\end{align*}
$$

Analogously, the optimal TCR $b^{*}$ is determined by

$$
\begin{align*}
0 & =-\tau^{*} r \widetilde{K}+\left[\tau^{*}\left(F_{K}-r b^{*}\right)+\left(1-\tau^{*}\right)\left[1-\beta \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \widetilde{K}}\right]\left(\frac{\partial \widetilde{K}}{\partial b}+\frac{r B_{1 b}}{r-\zeta_{1}}+\frac{r B_{2 b}}{r-\zeta_{2}}\right) \\
& +\left[\tau G_{K}+\left(1-\tau^{*}\right)\left[1-\beta \widetilde{L}^{d}\right] \frac{\partial \widetilde{w}}{\partial \widetilde{K}^{d}}\right]\left(\frac{\partial \widetilde{K}^{d}}{\partial b}+\frac{r B_{1 b} \psi_{21}}{r-\zeta_{1}}+\frac{r B_{2 b} \psi_{22}}{r-\zeta_{2}}\right) \tag{K.36}
\end{align*}
$$

Simulation. Figure (K.1) presents the time path of welfare $\Omega_{t}$ relative to welfare before reform, $\Omega_{0}$, for the four cases considered in the simulation in Section 5.2.


Figure K.1: Welfare effects for a change from $b=0$ to $b=b^{*}=0.279$ at time $t=0$ for $\epsilon=1, \nu=0.6$ (panel (K.1-A)), $\epsilon=1, \nu=0.75$ (panel (K.1-B)), $\epsilon=0.95, \nu=0.95$ (panel (K.1-C)), and $\epsilon=0.95, \nu=$ 0.85 (panel (K.1-D)).

## References

Hong, Q. and Smart, M. (2010). In praise of tax havens: International tax planning and foreign direct investment. European Economic Review, 54(1):82-95.

Kimball, M. S. (2014). The Effect of Uncertainty on Optimal Control Models in the Neighbourhood of a Steady State. The Geneva Risk and Insurance Review, 39:2-39.

Turnovsky, S. J. (1997). International Macroeconomic Dynamics, volume 1 of MIT Press Books. The MIT Press.

Wildasin, D. E. (2003). Fiscal competition in space and time. Journal of Public Economics, 87(11):2571-2588.

Wildasin, D. E. (2011). Fiscal competition for imperfectly-mobile labor and capital: A comparative dynamic analysis. Journal of Public Economics, 95(11):1312-1321.


[^0]:    ${ }^{1}$ The derivatives with respect to the labor inputs cancel out.

[^1]:    ${ }^{2}$ Kimball (2014) proposes the term "prevalue function" for $H_{t}$, as it is the maximization of $H_{t}$ that yields the value function.

